



Customizable,
High Quality, Heavy Duty,
Industrial-Grade Actuators

INDUSTRIAL MOTION

TiMOTION ELECTRONIC LINEAR ACTUATORS – MOTION TECHNOLOGY THAT HELPS PROVIDE A CLEANER, BETTER FUTURE

Many industrial applications require heavy-duty automation on a large scale — especially for agricultural, construction, mining, ventilation, and process control machinery, among others. The technology is out there, and it's only getting better. Equipment manufacturers are increasingly turning to electric linear actuators as a cost-efficient and reliable alternative to previous industry standards, such as hydraulic and pneumatic motion systems. TiMOTION's Industrial Motion product line is shown within this catalog, as well as additional information about what we offer and the full benefits of our linear actuator technology.

Features and Benefits of TiMOTION Actuation Systems for Industrial Applications

- Five year mechanical warranty
- Aluminum and steel construction
- Acme and ball screw drive
- Customization
- Clutch or internal limit switches
- Multiple feedback options
- Easy installation
- Excellent engineering support
- IP69K protection available
- Heavy duty construction
- Low maintenance
- Wide speed range

JP3

series



TiMOTION's JP3 series inline linear actuator was designed for low load industrial applications where up to IP69K dust and liquid ingress protection is necessary. It is best suited for applications with visual or compact installation dimension requirements. Hall sensors are optional for the JP3 which allow for synchronization and position feedback.

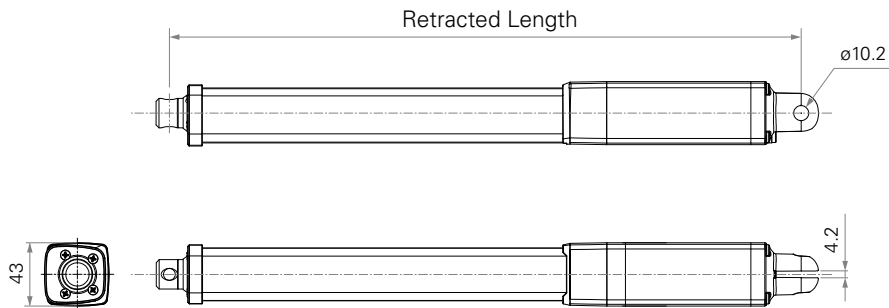
Load and Speed

	CODE	Load (N)		Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)
		Push	Pull		No Load 24V DC	With Load 24V DC	With Load 24V DC
Motor Speed (5600RPM)	B	2000	2000	2000	1.0	3.0	4.2
	C	1500	1500	1500	1.0	3.0	6.5
	D	1000	1000	1000	1.0	3.0	9.5
	E	500	500	500	1.0	3.0	20.0

NOTE

- 1 With a 12V motor, the current is approximately twice the current measured in 24V; speed will be similar for both voltages.
- 2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.

Standard Dimension (mm)



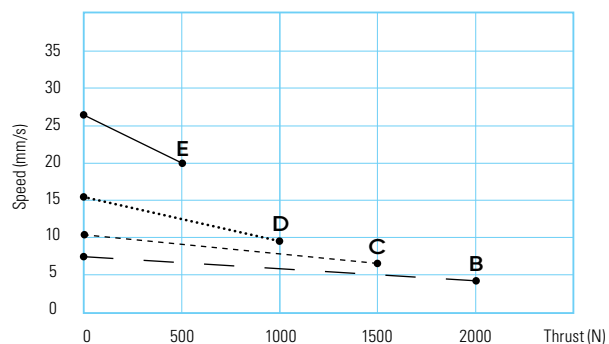
General Features

Maximum load	2,000N in push and pull
Maximum speed at full load	20mm/s (with 500N in a push or pull condition)
Stroke	20~500mm
Minimum installation dimension	Stroke+217mm
IP rating	Up to IP69K
Color	Black or grey
Operational temperature range	-5°C~+65°C
Operational temperature range at full performance	+5°C~+45°C
Storage temperature range	-40°C~+70°C
An inline actuator designed for small spaces	

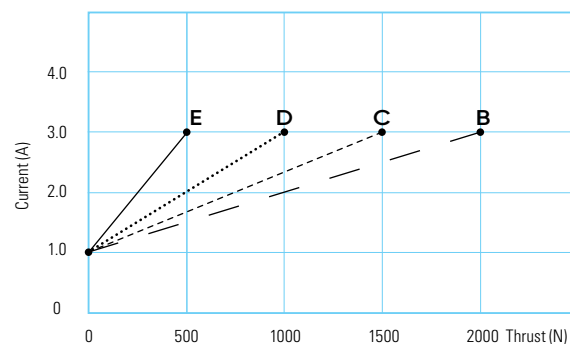
Performance Data

Motor Speed 5600RPM, Duty Cycle 10%

Speed vs. Thrust



Current vs. Thrust



NOTE

1 The performance data in the curve charts shows theoretical value.

JP3 Ordering Key

JP3

Version: 20161101-B

Voltage	1 = 12V DC	2 = 24V DC	5 = 24V DC, PTC
Load and Speed	See page 4		
Stroke (mm)			
Restracted Lengh (mm)	See page 8		
Rear Attachment (mm)	1 = Aluminum casting, U clevis, slot 4.2, depth 18, hole 10.2 See page 9		
Front Attachment (mm)	1 = Aluminum casting, no slot, hole 6.4 2 = Aluminum casting, no slot, hole 8 3 = Aluminum casting, U clevis, slot 6, depth 13, hole 10 4 = Aluminum casting, U clevis, slot 6, depth 13, hole 6.4 5 = Aluminum casting, U clevis, slot 6, depth 13, hole 8 See page 9		
Direction of Rear Attachment (Counterclockwise)	1 = 0° See page 9		
Color	1 = Black	2 = Grey (Pantone428C)	
IP Rating	1 = Without 2 = IP54	3 = IP66 5 = IP66W	6 = IP66D 7 = IP68 8 = IP69K
Special Functions for Spindle Sub-Assembly	0 = Without (standard)		
Functions for Limit Switches	1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to cut current + 3rd LS to send signal 3 = Two switches at full retracted / extended positions to send signal 4 = Two switches at full retracted / extended positions to send signal + 3rd LS to send signal		
Output Signals	0 = Without	1 = One Hall sensor	2 = Two Hall sensors
Connector	1 = DIN 6P, 90° plug See page 9		
Cable Length (mm)	0 = Straight, 100 1 = Straight, 500	3 = Straight, 1000 B~H = For direct cut system, please contact TiMOTION	

JP3

Ordering Key Appendix

Retracted Length (mm)







1. Calculate $A+B+C = Y$
2. Retracted length needs to $\geq \text{Stroke}+Y$

A. Attachment	Front Attachment Code	Rear Attachment Code
		1
	1	+217
	2	+217
	3	+230
	4	+230
	5	+230
B. Stroke (mm)	20~150	-
	151~200	-
	201~250	+5
	251~300	+10
	301~350	+15
	351~400	+20
C. Output Signals	Code	
	0	-
	1	+13
	2	+13

*For stroke over 400mm, +5mm for each increment of 50mm stroke

Functions for Limit Switches

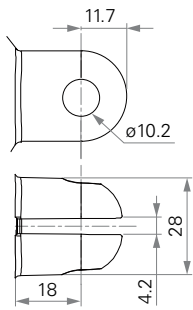
Wire Definitions

		CODE			
	Pin	1	2	3	4
 Green	1	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)
 Red	2	N/A	N/A	Common	Common
 White	3	N/A	Middle switch pinB	Upper limit switch	Upper limit switch
 Black	4	N/A	Middle switch pinA	N/A	Medium limit switch
 Yellow	5	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)
 Blue	6	N/A	N/A	Lower limit switch	Lower limit switch

NOTE

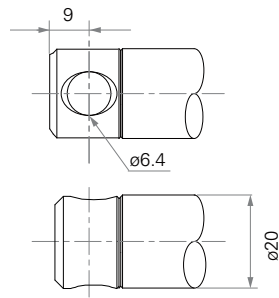
- 1 See ordering key - functions for limit switches.

Rear Attachment (mm)

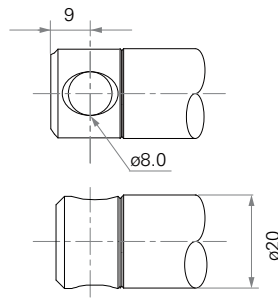


1 = Aluminum casting, U clevis, slot 4.2, depth 18, hole 10.2

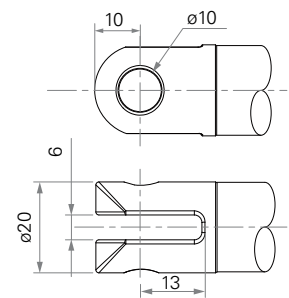
Front Attachment (mm)



1 = Aluminum casting, no slot, hole 6.4

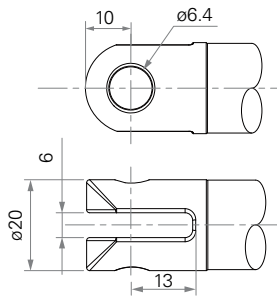


2 = Aluminum casting, no slot, hole 8

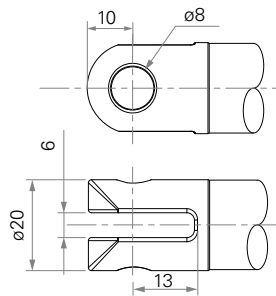


3 = Aluminum casting, U clevis, slot 6, depth 13, hole 10

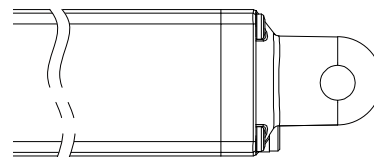
Direction of Rear Attachment Counterclockwise



4 = Aluminum casting, U clevis, slot 6, depth 13, hole 6.4

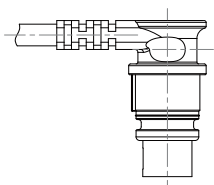


5 = Aluminum casting, U clevis, slot 6, depth 13, hole 8

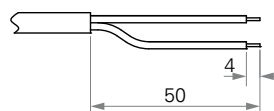


1 = 0°

Connector



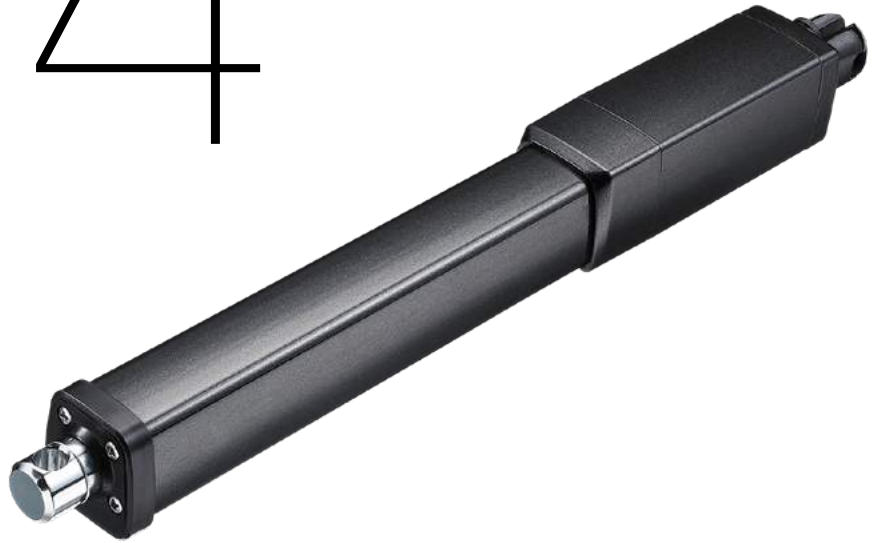
1 = DIN 6P, 90° plug



2 = Tinned leads

JP4

series



TiMOTION's JP4 series inline linear actuator is most similar to the JP3, but was designed for industrial applications that require higher load and speed. Its IP69K protection ensures it will withstand high temperature, high pressure water jets, and the ingress of dust and other solid contaminants. For synchronization and position feedback, the JP4 can be equipped with Hall sensors.

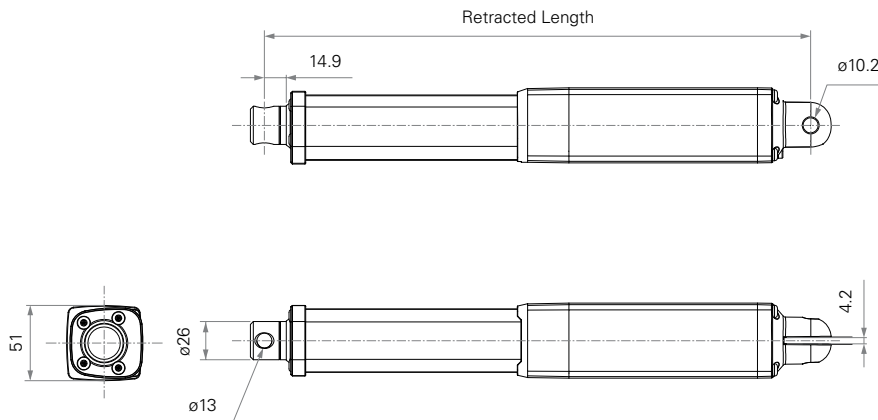
Load and Speed

	CODE	Load (N)		Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)	
		Push	Pull		No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (3800RPM)	B	4500	3000	4500	0.8	3.5	5.1	3.2
	C	3500	3000	3000	0.8	3.2	7.3	4.8
	D	2500	2500	2000	0.8	3.2	10.0	6.2
	E	1500	1500	1000	0.8	2.2	13.0	10.3
	F	1000	1000	700	0.8	2.2	19.0	15.5
	G	500	500	500	0.8	2.0	29.0	24.0

NOTE

- 1 With a 12V motor, the current is approximately twice the current measured in 24V; speed will be similar for both voltages.
- 2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.

Standard Dimension (mm)



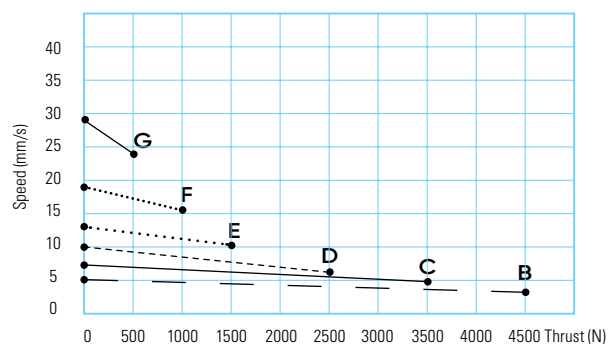
General Features

Maximum load	4,500N in push
Maximum load	3,000N in pull
Maximum speed at full load	24mm/s (with 500N in a push or pull condition)
Minimum installation dimension	Stroke+289mm
Stroke	20~500mm
IP rating	Up to IP69K
Color	Black or grey
Operational temperature range	-5°C~+65°C
Operational temperature range at full performance	+5°C~+45°C
Storage temperature range	-40°C~+70°C
An inline actuator designed for small spaces	

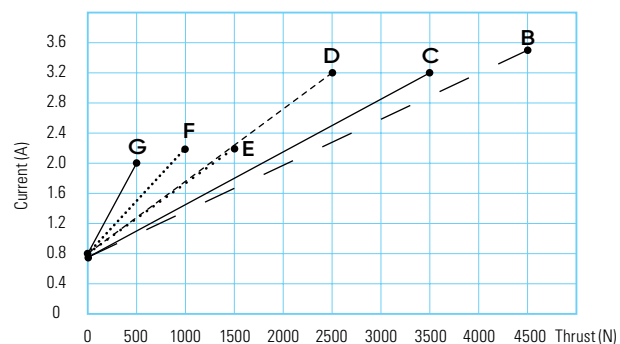
Performance Data

Motor Speed 3800RPM, Duty Cycle 10%

Speed vs. Thrust



Current vs. Thrust



NOTE

¹ The performance data in the curve charts shows theoretical value.

JP4 Ordering Key

JP4

Version: 20161101-B

Voltage	1 = 12V DC	2 = 24V DC	5 = 24V DC, PTC
Load and Speed	See page 10		
Stroke (mm)			
Restracted Lenght (mm)	See page 14		
Rear Attachment (mm)	1 = Aluminum casting, U clevis, slot 4.2, depth 18, hole 10.2 See page 15		
Front Attachment (mm)	1 = #45 Steel CNC, no slot, hole 13 See page 15		
Direction of Rear Attachment (Counterclockwise)	1 = 0° See page 15		
Color	1 = Black	2 = Grey (Pantone428C)	
IP Rating	1 = Without 2 = IP54	3 = IP66 5 = IP66W	6 = IP66D 7 = IP68 8 = IP69K
Special Functions for Spindle Sub-Assembly	0 = Without (standard)		
Functions for Limit Switches	1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to cut current + 3rd LS to send signal 3 = Two switches at full retracted / extended positions to send signal 4 = Two switches at full retracted / extended positions to send signal + 3rd LS to send signal		
Output Signals	0 = Without	1 = One Hall sensor	2 = Two Hall sensors
Connector	1 = DIN 6P, 90° plug See page 15		
Cable Length (mm)	0 = Straight, 100 1 = Straight, 500	3 = Straight, 1000 B~H = For direct cut system, please contact TiMOTION	

JP4

Ordering Key Appendix

Retracted Length (mm)







1. Calculate $A+B+C = Y$
2. Retracted length needs to $\geq \text{Stroke}+Y$

A. Attachment	Front Attachment Code	Rear Attachment Code
		1
	1	+289
B. Stroke (mm)	20~150	-
	151~200	-
	201~250	+10
	251~300	+20
	301~350	+30
	351~400	+40

*For stroke over 400mm, +10mm for each increment of 50mm stroke

Functions for Limit Switches

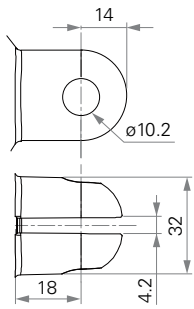
Wire Definitions

Wire Definitions			CODE			
		Pin	1	2	3	4
	Green	1	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)
	Red	2	N/A	N/A	Common	Common
	White	3	N/A	Middle switch pinB	Upper limit switch	Upper limit switch
	Black	4	N/A	Middle switch pinA	N/A	Medium limit switch
	Yellow	5	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)
	Blue	6	N/A	N/A	Lower limit switch	Lower limit switch

NOTE

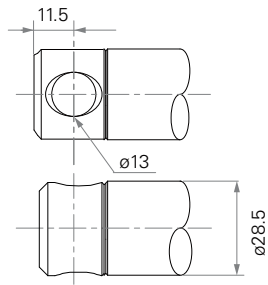
- 1 See ordering key - functions for limit switches.

Rear Attachment (mm)



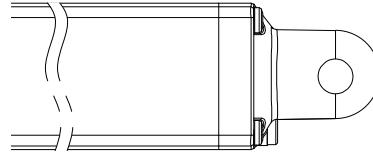
1 = Aluminum casting, U clevis,
slot 4.2, depth 18, hole 10.2

Front Attachment (mm)



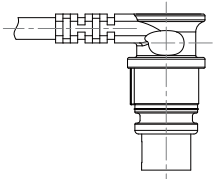
1 = #45 Steel CNC, no slot,
hole 13

Direction of Rear Attachment Counterclockwise

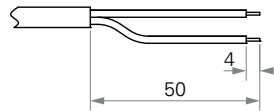


1 = 0°

Connector



1 = DIN 6P, 90° plug



2 = Tinned leads

MA1

series



TiMOTION's MA1 series linear actuator is the proven choice for applications requiring a durable, long life solution. Specifically designed for harsh working environments, the MA1 linear actuator is ideal for use in heavy-duty machinery, industrial equipment and off road vehicles. This linear actuator has been certified for applications requiring IP66 dynamic compliance. Available options for the MA1 linear actuator include AC or DC power, ball or acme spindles, mechanical or electrical braking and a load limiting clutch or limit switches.

Load and Speed

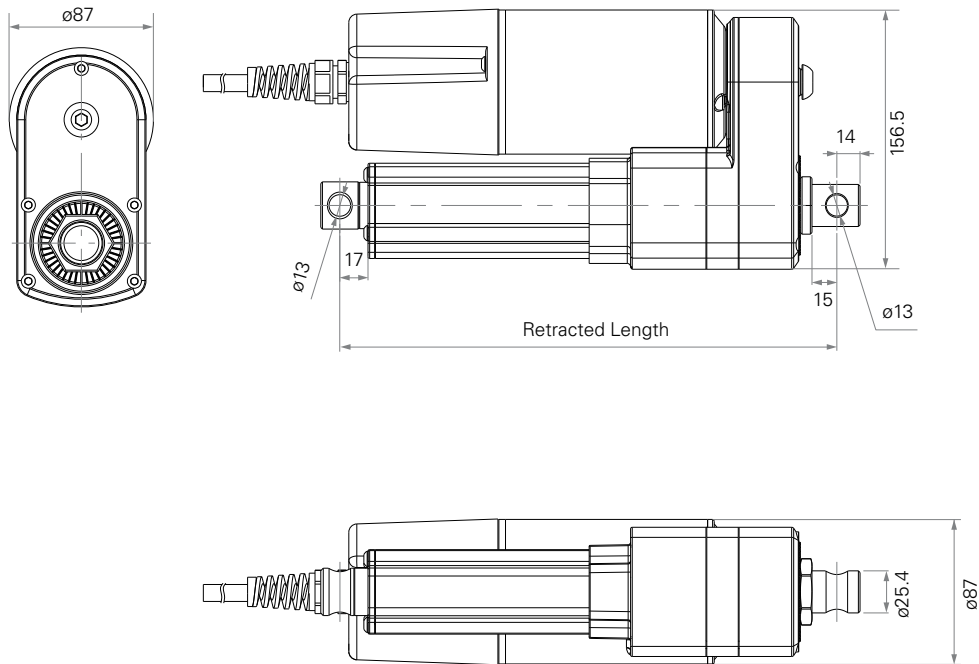
	CODE	Load (N)		Typical Current (A)				Typical Speed (mm/s)				Overload Clutch Range (N)
		Push	Pull	No Load 12V DC	24V DC	With Load 12V DC	24V DC	No Load 12V DC	24V DC	With Load 12V DC	24V DC	
ACME Screw, DC Motor	B	1500	1500	10.0	5.0	15.4	7.7	29.5	29.5	27.0	27.0	1800~3300
	C	2500	2500	5.0	2.5	14.0	7.0	15.8	15.8	14.3	14.3	3000~5500
Ball Screw, DC Motor	A	2500	2500	7.0	3.5	30.0	12.5	58.5	58.5	36.5	48.0	3000~5500
	B	3500	3500	5.0	2.5	18.0	9.0	29.8	29.8	25.5	25.5	4200~7700
	C	4500	4500	4.0	2.0	13.0	6.5	16.0	16.0	14.0	14.0	5400~9900

	CODE	Load (N)		Typical Current (A)				Typical Speed (mm/s)				Overload Clutch Range (N)
		Push	Pull	No Load 110V AC	220V AC	With Load 110V AC	220V AC	No Load 110V AC	220V AC	With Load 110V AC	220V AC	
ACME Screw, AC Motor	B	1500	1500	1.9	0.9	2.0	1.0	26.1	22.5	23.0	21.0	1800~3300
	C	2500	2500	1.9	0.9	2.0	1.0	14.1	12.0	12.8	11.2	3000~5500
Ball Screw, AC Motor	A	2500	2500	2.0	0.9	2.5	1.3	53.0	46.0	38.5	40.0	3000~5500
	B	3500	3500	1.9	0.9	2.1	1.1	27.0	23.5	22.5	21.5	4200~7700
	C	4500	4500	1.9	0.9	2.0	1.0	14.5	12.0	13.0	11.5	5400~9900

NOTE

- 1 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.
- 2 Current and speed: Tested average value when stretching in push direction.
- 3 Standard stroke (ACME): 20~1000mm. Standard stroke (BALL): 50~1000mm.

Standard Dimension (mm)



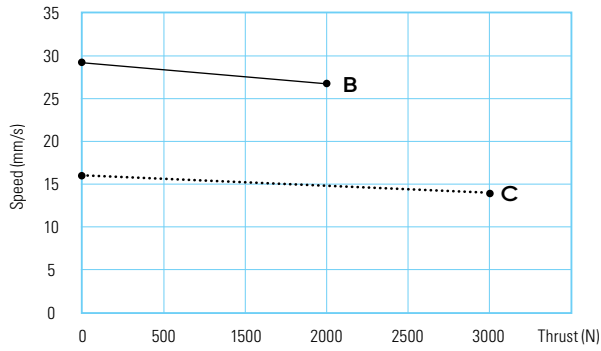
General Features

Spindle	ACME or Ball screw
Maximum load	4,500N in push and pull
Maximum speed at full load	48mm/s (Ball screw, 24V DC motor, with 2500N)
Minimum installation dimension	Stroke+160mm (without POT)
IP rating	IP66D
Operational temperature range	-30°C~+65°C
Operational temperature range at full performance	+5°C~+45°C
Options	Overload clutch, Hall sensor(s), POT, manual drive function
Mechanical or electromagnetic brake	
Higher duty cycle (20%), corrosion proof	

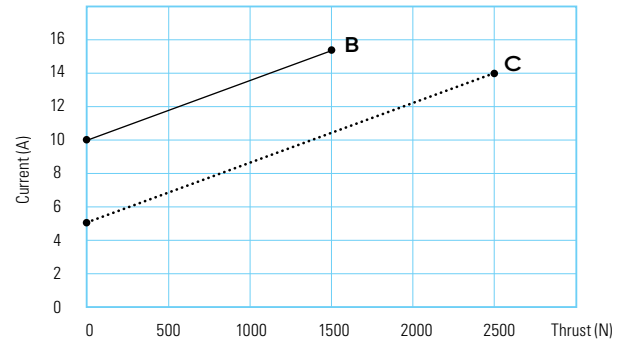
Performance Data

ACME Screw 12V DC Motor, Duty Cycle 25%

Speed vs. Thrust

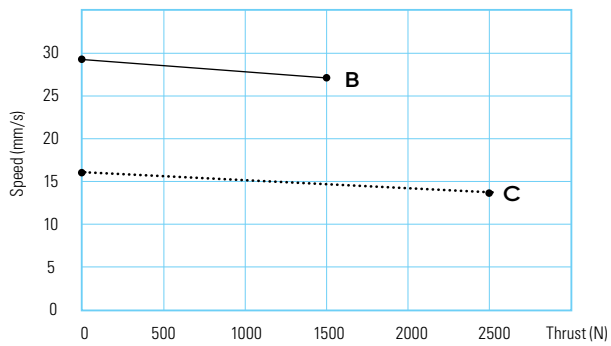


Current vs. Thrust

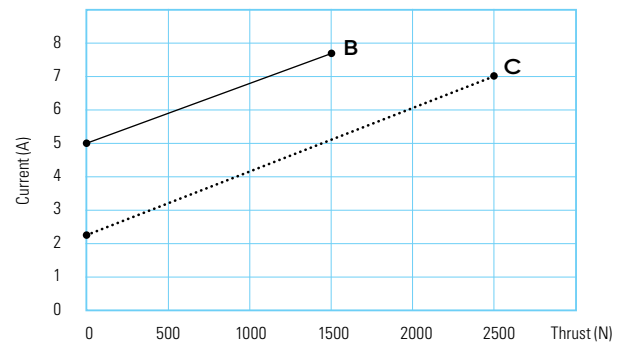


ACME Screw 24V DC Motor, Duty Cycle 25%

Speed vs. Thrust



Current vs. Thrust



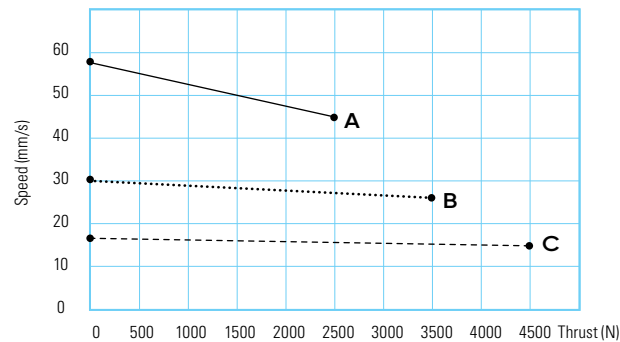
NOTE

- 1 The performance data in the curve charts shows theoretical value.

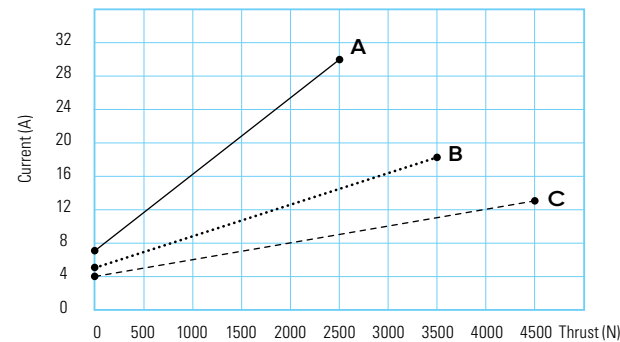
Performance Data

Ball Screw 12V DC Motor, Duty Cycle 25%

Speed vs. Thrust

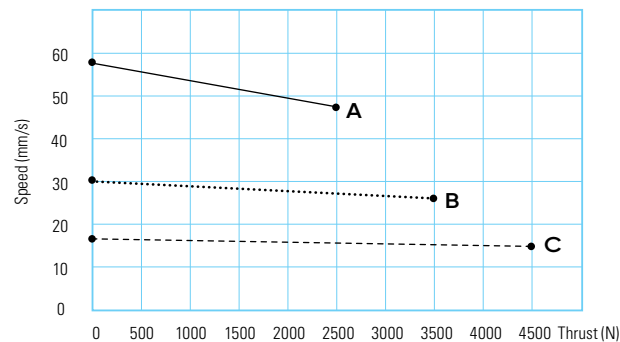


Current vs. Thrust

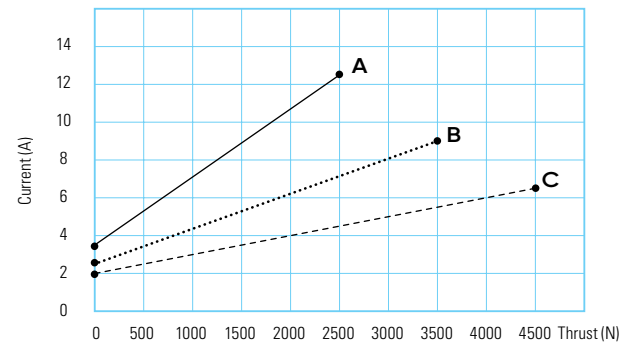


Ball Screw 24V DC Motor, Duty Cycle 25%

Speed vs. Thrust



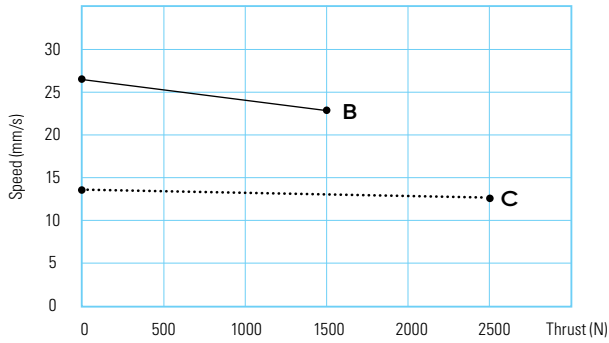
Current vs. Thrust



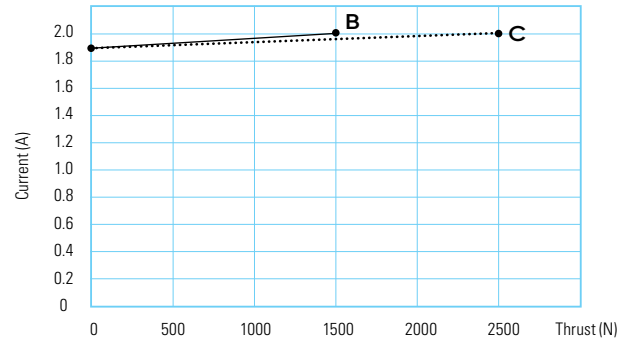
Performance Data

ACME Screw 110V AC Motor, Duty Cycle 25%

Speed vs. Thrust

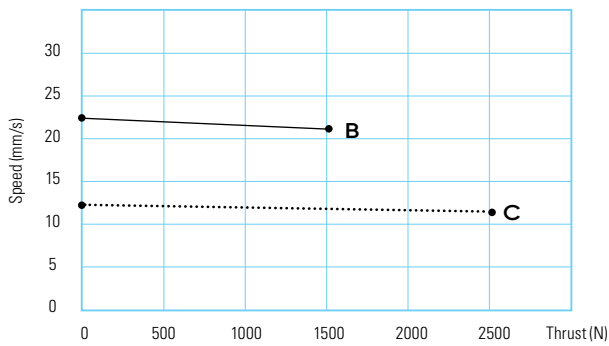


Current vs. Thrust

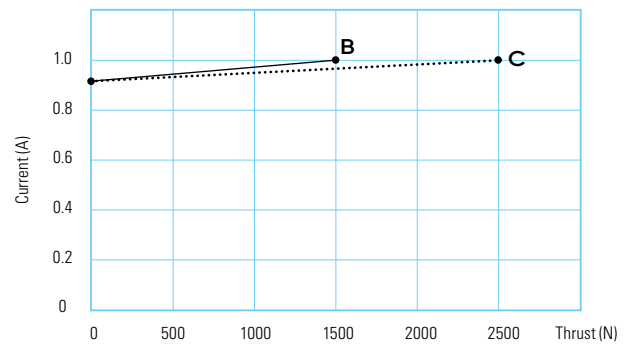


ACME Screw 220V AC Motor, Duty Cycle 25%

Speed vs. Thrust



Current vs. Thrust



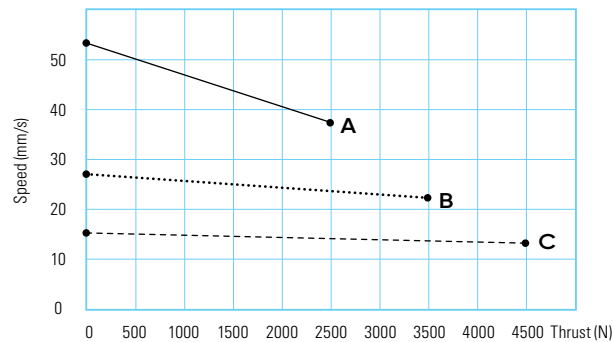
NOTE

1 The performance data in the curve charts shows theoretical value.

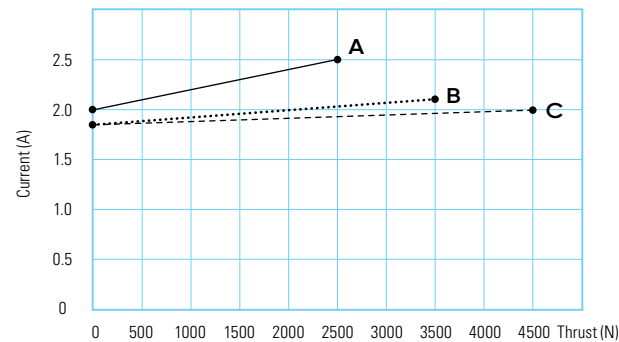
Performance Data

Ball Screw 110V AC Motor, Duty Cycle 25%

Speed vs. Thrust

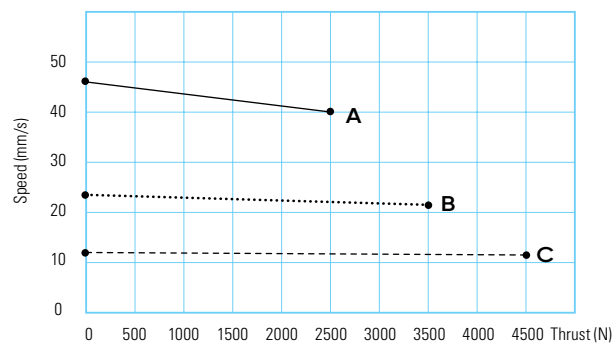


Current vs. Thrust

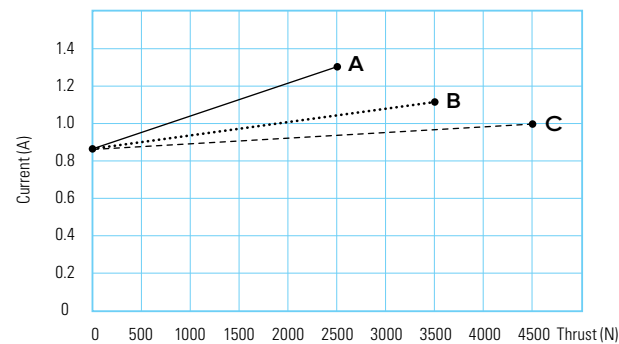


Ball Screw 220V AC Motor, Duty Cycle 25%

Speed vs. Thrust



Current vs. Thrust



MA1 Ordering Key

MA1

Version: 20170710-B

Spindle Type	A = ACME screw	B = Ball screw	
Voltage	1 = 12V DC 2 = 24V DC	3 = 36V DC 4 = 110V AC 60Hz	5 = 220V AC 50Hz
Load and Speed	See page 16		
Stroke (mm)			
Restracted Lengh (mm)	See page 23		
Rear Attachment (mm)	1 = #45 Steel CNC, without slot, hole 13 See page 25		
Front Attachment (mm)	1 = #45 Steel CNC, without slot, hole 13 See page 25		
Direction of Rear Attachment (Counterclockwise)	1 = 90° (Standard) See page 25	2 = 0°	
Functions for Limit Switches	0 = Without (Needs to choose overload clutch) 1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to send signal		
Overload Clutch	0 = Without	1 = With (Standard)	
Mechanical Brake	0 = Without	1 = With (Ball screw's standard option)	
Electromagnetic Brake	0 = Without (Standard)	1 = With	
IP Rating	6 = IP66D		
Manual Drive	0 = Without	1 = With	
Output Signals	0 = Without 1 = POT	4 = One Hall sensor 5 = Two Hall sensors	
Connector	1 = Tinned leads		
Cable Length (mm)	1 = Straight, 500		

MA1

Ordering Key Appendix

Retracted Length (mm)

1. Calculate $A+B+C = Y$
2. Retracted length needs to $\geq \text{Stroke}+Y$

A. Type				
	ACME Screw DC Motor	Ball Screw DC Motor	ACME Screw AC Motor	Ball Screw AC Motor
	+160	+201	+160	+201

B. Mechanical Brake	Code	Type			
		ACME Screw DC Motor	Ball Screw DC Motor	ACME Screw AC Motor	Ball Screw AC Motor
	0	-	-	-	-
	1	+35	-	+35	-

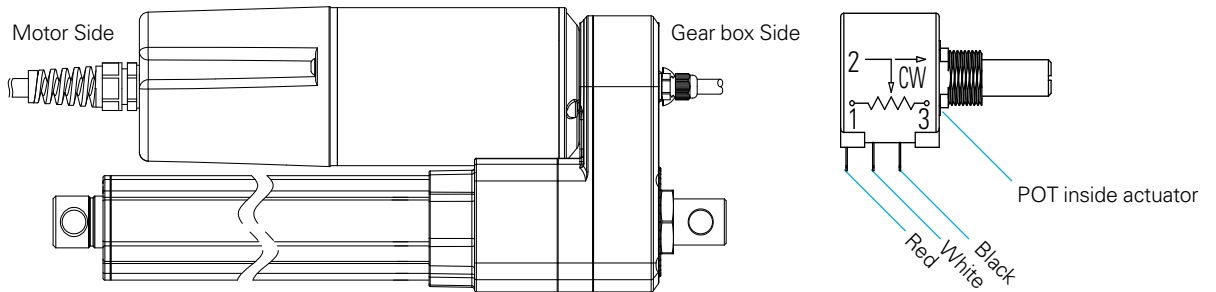
C. Output Signal	Code	Type			
		ACME Screw DC Motor	Ball Screw DC Motor	ACME Screw AC Motor	Ball Screw AC Motor
	0	-	-	-	-
	1	+36	+40	+36	+40
	4	-	-	+36	+40
	5	-	-	+36	+40

*For long stroke, there is no need for additional retracted length.

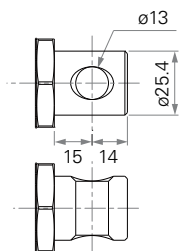
Functions for Limit Switches

Wire Definitions

				Output signal code			
				0 Without	1 POT	4 1 Hall	5 2 Hall
DC motor	Motor side	● Black	26	-	-	GND	GND
		● Blue	26	-	-		S2
		○ White	26	-	-	S1	S1
		● Red	26	-	-	+5V	+5V
		● Green	16	Extend+	Extend+	Extend+	Extend+
		● Yellow	16	Extend+	Extend+	Extend+	Extend+
	Gear box side	● Red	26	-	Pin 1	-	-
		○ White	26	-	Pin 2	-	-
		● Black	26	-	Pin 3	-	-
AC motor	Motor side	● Black	18	Extend+	Extend+	Extend+	Extend+
		● Grey	18	Extend+	Extend+	Extend+	Extend+
		● Brown	18	PCBA+	PCBA+	PCBA+	PCBA+
		● Blue	18	Neutral	Neutral	Neutral	Neutral
		● Green/Yellow	18	GND	GND	GND	GND
	Gear box side	● Red	20	-	Pin1	+5V	+5V
		○ White	20	-	Pin2	S1	S1
		● Blue	20	-	-	-	S2
		● Black	20	-	Pin3	GND	GND

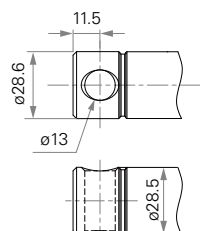


Rear Attachment (mm)



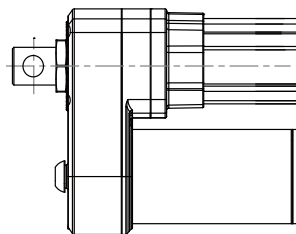
1 = #45 Steel CNC, without slot, hole 13

Front Attachment (mm)

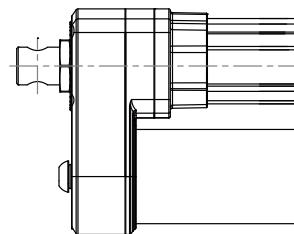


1 = #45 Steel CNC, without slot, hole 13

Direction of Rear Attachment Counterclockwise

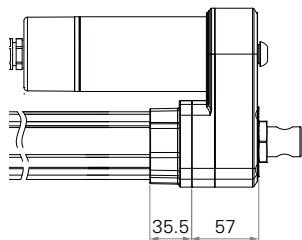


1 = 90°

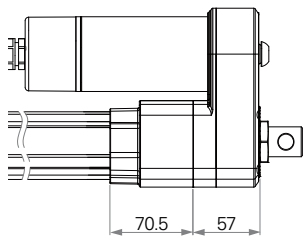


2 = 0°

Mechanical Brake

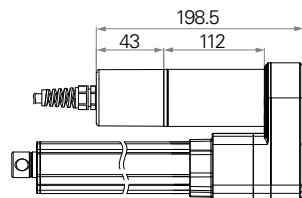


0 = Without

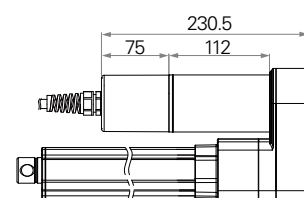


1 = With
(Ball screw's standard option)

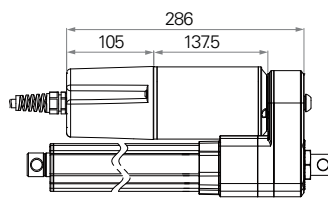
Electromagnetic Brake



0 = Without
(Standard, DC Motor)



1 = With
(DC Motor)



1 = Without
(Standard, AC Motor)

MA2

series



TiMOTION's MA2 series linear actuator was specifically designed for applications which face harsh working environments and require ruggedness and durability. Its IP69K protection ensures it will withstand high temperature, high pressure water jets, and the ingress of dust and other solid contaminants. The MA2 also has optional Reed switches along the outer tube which allow users to adjust the stroke length. For improved control and accuracy of motion, the MA2 can be customized with many different feedback options depending on your application requirements. Example applications suitable for the MA2: Agricultural equipment such as spreaders, harvesters, grain handlers, combines and tractors.

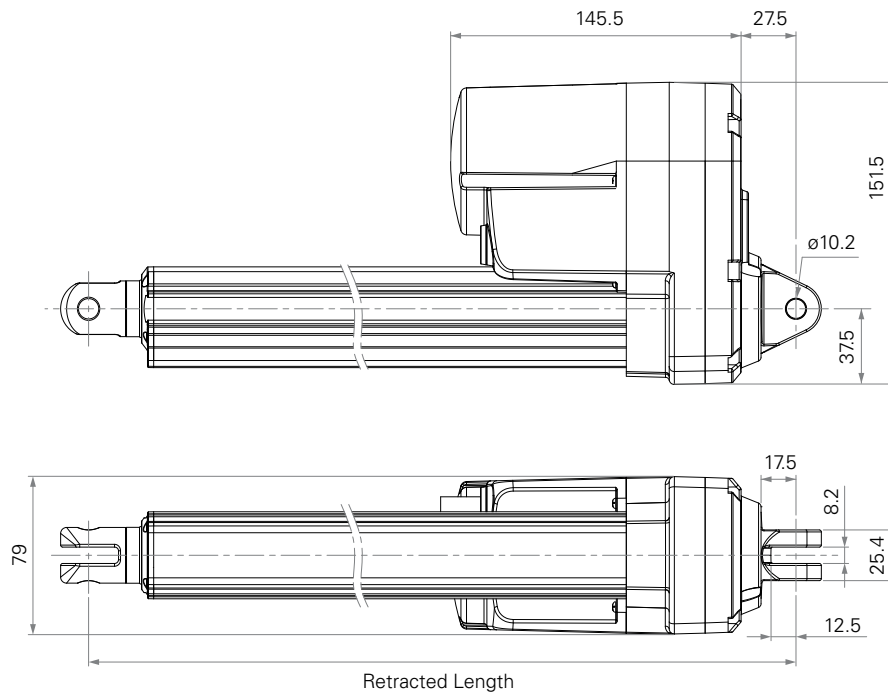
Load and Speed

	CODE	Load (N)		Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)	
		Push	Pull		No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (5200RPM)	F	1000	1000	1300	2.5	9.0	54.0	45.0
	G	2000	2000	2600	2.2	9.0	28.5	22.0
	H	4000	4000	5200	2.0	8.5	14.0	11.7
	J	6000	6000	7800	2.0	7.0	7.0	6.2

NOTE

- 1 With a 12V motor, the current is approximately twice the current measured in 24V. With a 36V motor, the current is approximately two-thirds the current measured in 24V; speed will be similar for both voltages.
- 2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMotion control boxes have this feature built-in.

Standard Dimension (mm)



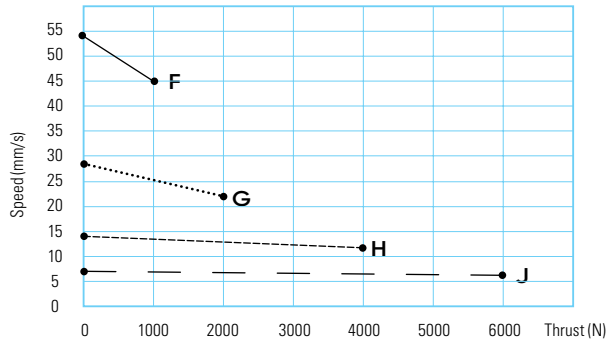
General Features

Maximum load	6,000N in push and pull
Maximum speed at full load	45mm/s (with 1000N in a push or pull condition)
Stroke	25~1000mm
Minimum installation dimension	Stroke+131mm
IP rating	Up to IP69K
Operational temperature range	-30°C~+65°C
Operational temperature range at full performance	+5°C~+45°C
Options	Hall sensor(s), POT

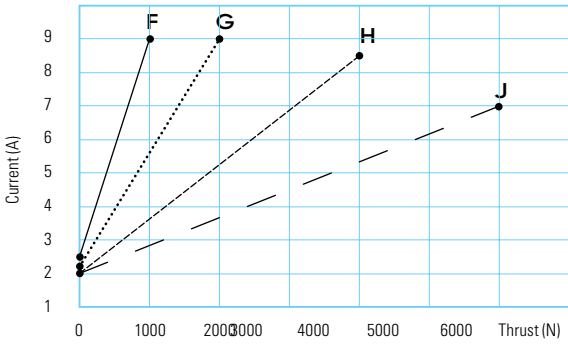
Performance Data

Motor Speed 5200RPM, Duty Cycle 25%

Speed vs. Thrust



Current vs. Thrust



NOTE

1 The performance data in the curve charts shows theoretical value.

MA2 Ordering Key

MA2

Version: 20170411-B

Voltage	1 = 12V DC 2 = 24V DC	3 = 36V DC 5 = 24V, thermal control	6 = 12V, thermal control 7 = 36V, thermal control
Load and Speed	See page 26		
Stroke (mm)			
Restracted Lengh (mm)	See page 30		
Rear Attachment (mm) See page 32	1 = Aluminum casting, clevis U, slot 8.2, depth 12.5, hole 10.2 2 = Aluminum casting, clevis U, slot 8.2, depth 15, hole 10.2 3 = Aluminum casting, clevis U, slot 8.2, depth 15, hole 12.8		
Front Attachment (mm) See page 32	1 = Iron inner tube with punched hole, without slot, hole 10.2 3 = Iron inner tube with punched hole, without slot, hole 12.8 4 = Aluminum casting, clevis U, slot 8.2, depth 15, hole 10.2 6 = Aluminum casting, clevis U, slot 8.2, depth 15, hole 12.8 K = Rod end bearing, hole 12.8		
Direction of Rear Attachment (Counterclockwise)	1 = 90° See page 32	2 = 0°	
Functions for Limit Switches	1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to cut current + third one in between to send signal 3 = Two switches at full retracted / extended positions to send signal 4 = Two switches at full retracted / extended positions to send signal + third one in between to send signal		
Output Signals	0 = Without 1 = POT 4 = One Hall sensor	5 = Two Hall sensors 6 = One Reed sensors on outer tube 7 = Two Reed sensors on outer tube	
Connector See page 33	2 = Tinned leads		
Cable Length (mm)	1 = Straight, 500 2 = Straight, 1000	3 = Straight, 1500 4 = Straight, 2000	
IP Rating	1 = Without	2 = IP54	6 = IP66D 8 = IP69K
Manual Drive	0 = Without	1 = With	
T-Smart	0 = Without		

MA2

Ordering Key Appendix

Retracted Length (mm)







1. Calculate $A+B+C = Y$
2. Retracted length needs to $\geq \text{Stroke}+Y$

A. Attachment	Front Attachment Code	Rear Attachment Code	
		1	2,3
	1,3	+131	+134
	4,6	+161	+164
	K	+178	+181
B. Stroke (mm)	0~150	-	
	151~200	-	
	201~250	+10	
	251~300	+20	
	301~350	+30	
	351~400	+40	
C. Output Signals	Code		
	0,4,5,6,7	-	
	1	+20	

*For stroke over 400mm, +10mm for each increment of 50mm stroke

Functions for Limit Switches

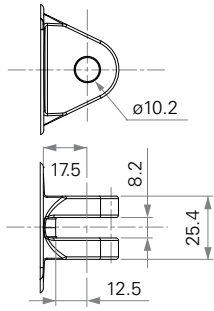
Wire Definitions

Wire Definitions			CODE			
		Pin	1	2	3	4
	Green	1	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)
	Red	2	N/A	N/A	Common	Common
	White	3	N/A	Middle switch pinB	Upper limit switch	Upper limit switch
	Black	4	N/A	Middle switch pinA	N/A	Medium limit switch
	Yellow	5	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)
	Blue	6	N/A	N/A	Lower limit switch	Lower limit switch

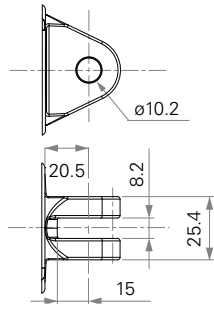
NOTE

¹ See ordering key - functions for limit switches.

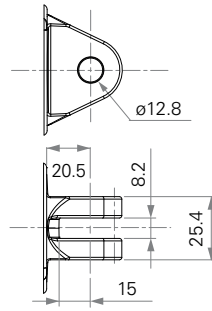
Rear Attachment (mm)



1 = Aluminum casting, clevis U, slot 8.2, depth 12.5, hole 10.2

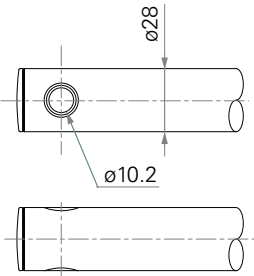


2 = Aluminum casting, clevis U, slot 8.2, depth 15, hole 10.2

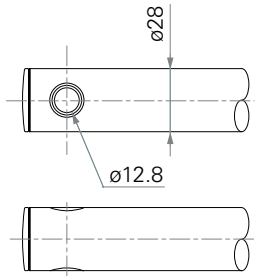


3 = Aluminum casting, clevis U, slot 8.2, depth 15, hole 12.8

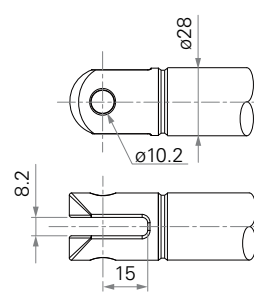
Front Attachment (mm)



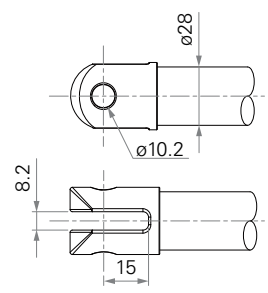
1 = Iron inner tube with punched hole, without slot, hole 10.2



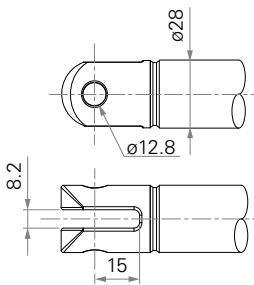
3 = Iron inner tube with punched hole, without slot, hole 12.8



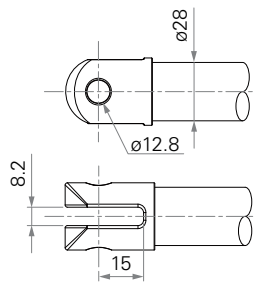
4 = Aluminum casting, clevis U, slot 8.2, depth 15, hole 10.2 (IP: IP66D, IP69K)



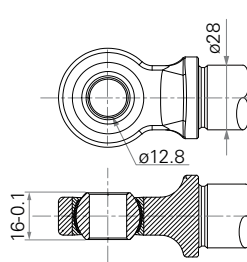
4 = Aluminum casting, clevis U, slot 8.2, depth 15, hole 10.2 (IP: Without, IP54)



6 = Aluminum casting, clevis U, slot 8.2, depth 15, hole 12.8 (IP: IP66D, IP69K)



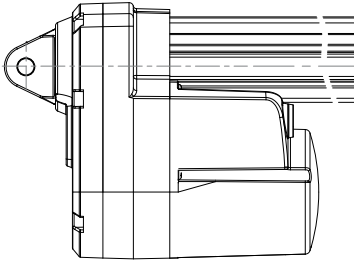
6 = Aluminum casting, clevis U, slot 8.2, depth 15, hole 12.8 (IP: Without, IP54)



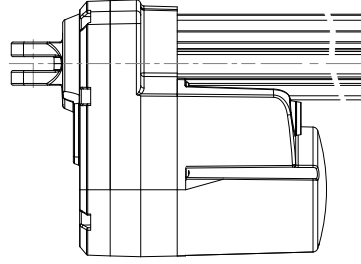
K = Rod end bearing, hole 12.8

Direction of Rear Attachment

Counterclockwise

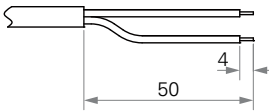


1 = 90°



2 = 0°

Connector



2 = Tinned leads

TA2

series



TiMOTION's TA2 series linear actuator is compact, robust and capable of performing well in certain outdoor environments. This linear actuator is perfect for use in small spaces where force or capability cannot be sacrificed. Options include feedback sensors, signal sending limit switches and 90 degree clevis mounting. Industry certifications for the TA2 linear actuator include EN60601-1, EMC, and RoHS.

Load and Speed

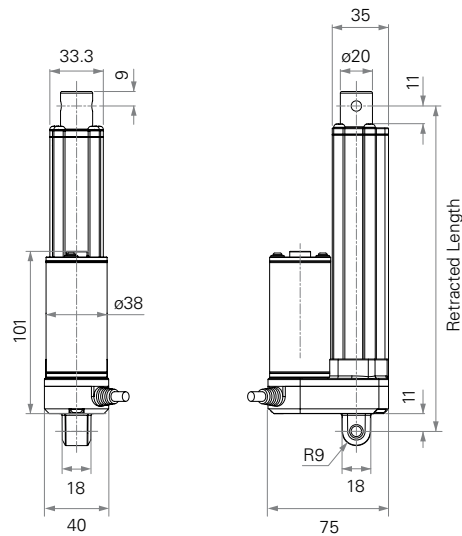
	CODE	Load (N)		Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)		Noise (db)
		Push	Pull		No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC	
Motor Speed (4200RPM)	A	120	120	120	0.8	1.2	44.0	32.0	≤ 70
	B	240	240	240	0.7	1.2	22.0	16.5	≤ 70
	C	500	500	500	0.6	1.0	11.0	8.5	≤ 68
	D	750	750	750	0.6	1.0	7.5	6.2	≤ 68
	E	1000	1000	1000	0.6	1.0	5.6	4.6	≤ 68
Motor Speed (6000RPM)	F	120	120	120	1.0	1.8	67.5	51.0	≤ 74
	G	240	240	240	0.9	1.8	33.5	26.5	≤ 74
	H	500	500	500	0.8	1.5	17.0	14.0	≤ 70
	K	750	750	750	0.8	1.5	11.0	10.0	≤ 70
	L	1000	1000	1000	0.8	1.5	9.0	7.6	≤ 70

NOTE

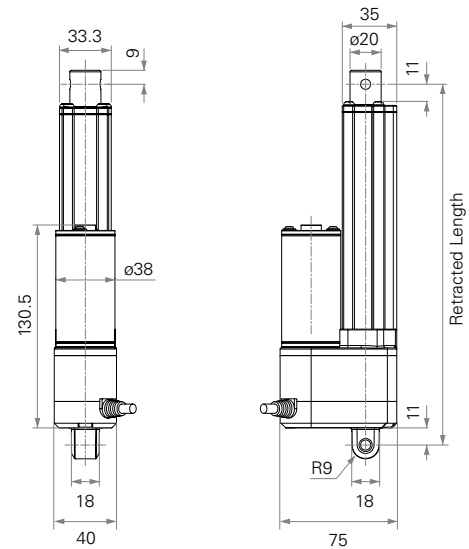
- 1 Motor 12V current is around 2 times in 24V; Motor 36V current is around 2/3 in 24V; Motor 48V current is around 1/2 in 24V; speed is around the same.
- 2 Above self lock performance needs working with Timotion control system in push direction.
- 3 Please refer to approval drawing for final value.
- 4 Environmental noise ≤ 38db

Standard Dimension (mm)

Without
Output Signal



Output Signal
#1, 2, 3, 4, 5



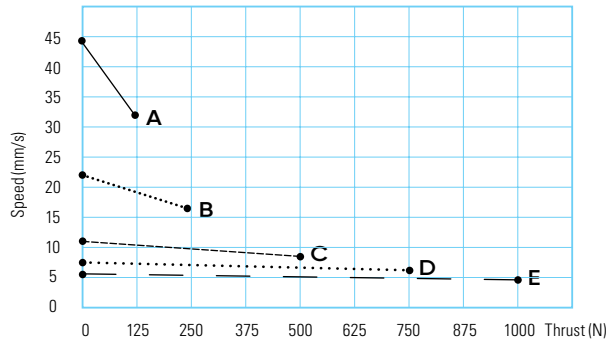
General Features

Maximum load	1,000N in push and pull
Maximum speed at full load	51mm/s (with 120N in a push or pull condition)
Stroke	20~1000mm
Minimum installation dimension	Stroke+105mm (without output signals)
Operational temperature range	Load < 500N: +5°C~+45°C Load ≥ 500N: -25°C~+65°C
Operational temperature range at full performance	+5°C~+45°C
IP rating	Up to IP66D
Options	POT, Optical, or Hall/ Reed sensor(s)
Compact size for limited space	

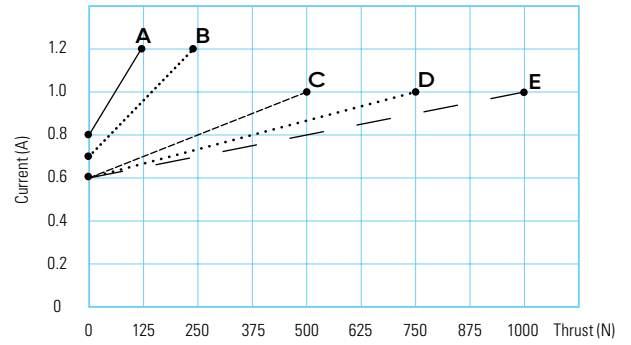
Performance Data

Motor Speed 4200RPM, Duty Cycle 25%

Speed vs. Thrust

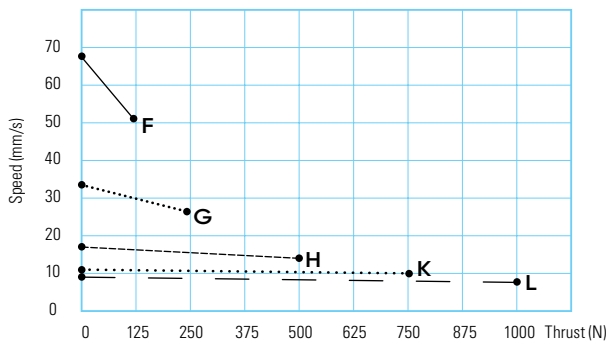


Current vs. Thrust

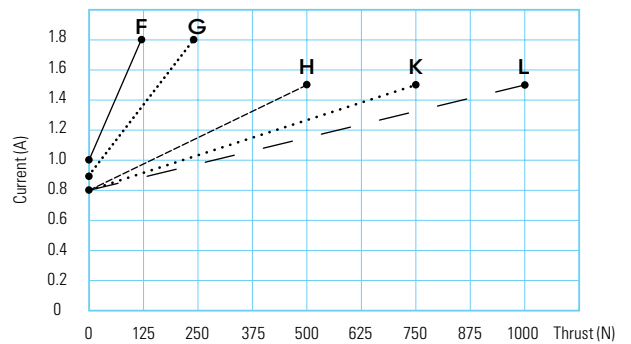


Motor Speed 6000RPM, Duty Cycle 25%

Speed vs. Thrust



Current vs. Thrust



NOTE

- 1 The performance data in the curve charts shows theoretical value.
- 2 See ordering key - functions for limit switches.

TA2 Ordering Key

TA2

Version: 20160711-M

Voltage	1 = 12V DC 2 = 24V DC	3 = 36V DC 4 = 48V DC	5 = 24V DC, PTC
Load and Speed	See page 34		
Stroke (mm)			
Restracted Lengh (mm)	See page 38		
Rear Attachment (mm) See page 40	1 = Aluminum casting, hole 6.4, one piece casting with gear box 2 = Aluminum casting, hole 8, one piece casting with gear box 3 = Aluminum casting, hole 10, one piece casting with gear box 4 = Aluminum casting, clevis U, slot 6, depth 10.5, hole 6.4, one piece casting with gear box 5 = Aluminum casting, clevis U, slot 6, depth 10.5, hole 8, one piece casting with gear box 6 = Aluminum casting, clevis U, slot 6, depth 10.5, hole 10, one piece casting with gear box		
Front Attachment (mm) See page 40	1 = Aluminum casting, no slot, hole 6.4 2 = Aluminum casting, no slot, hole 8 3 = Aluminum casting, U clevis, slot 6, depth 16, hole 10 4 = Aluminum casting, U clevis, slot 6, depth 16, hole 6.4 5 = Aluminum casting, U clevis, slot 6, depth 16, hole 8		
Direction of Rear Attachment (Counterclockwise)	1 = 90° See page 41	2 = 0°	
Functions for Limit Switches	1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to cut current + 3rd one in between to send signal 3 = Two switches at full retracted / extended positions to send signal 4 = Two switches at full retracted / extended positions to send signal + 3rd one in between to send signal		
Output Signals	0 = Without 1 = POT	2 = Optical 3 = Reed sensor	4 = One Hall sensor 5 = Two Hall sensors
Connector See page 41	1 = DIN 6P, 90° plug	2 = Tinned leads	
Cable Length (mm)	1 = Straight, 300 2 = Straight, 600	3 = Straight, 1000 B~H = For direct cut system, please contact TiMOTION	
IP Rating	1 = Without	2 = IP54	3 = IP66 6 = IP66D

TA2

Ordering Key Appendix

Retracted Length (mm)







1. Calculate $A+B+C = Y$
2. Retracted length needs to $\geq \text{Stroke}+Y$

A. Attachment	Front Attachment Code	Rear Attachment Code	
		1,2,3	4,5,6
	1	+105	+109
	2	+105	+109
	3	+115	+119
	4	+115	+119
	5	+115	+119
B. Stroke (mm)	~150	-	
	151~200	+2	
	201~250	+2	
	251~300	+2	
	301~350	+12	
	351~400	+22	
C. Output Signal	Code		
	0	-	
	1	+30	
	2	+30	
	3	+30	
	4	+30	
	5	+30	

*For stroke over 400mm, +10mm for each increment of 50mm stroke

Functions for Limit Switches

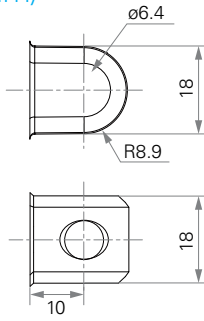
Wire Definitions

Wire Definitions			CODE			
		Pin	1	2	3	4
	Green	1	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)
	Red	2	N/A	N/A	Common	Common
	White	3	N/A	Middle switch pinB	Upper limit switch	Upper limit switch
	Black	4	N/A	Middle switch pinA	N/A	Medium limit switch
	Yellow	5	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)
	Blue	6	N/A	N/A	Lower limit switch	Lower limit switch

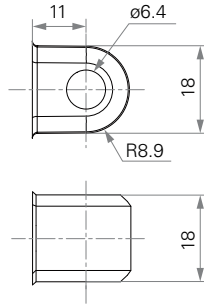
NOTE

¹ See ordering key - functions for limit switches.

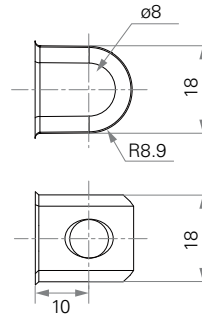
Rear Attachment (mm)



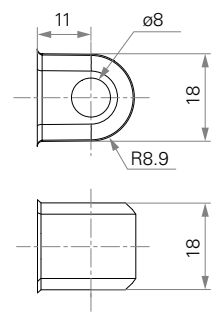
1 = Aluminum casting, hole 6.4, one piece casting with gear box.
Direction of rear attachment (counterclockwise): 0°



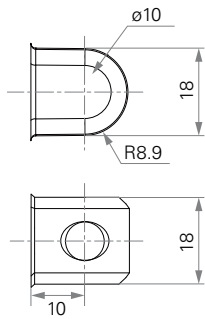
1 = Aluminum casting, hole 6.4, one piece casting with gear box.
Direction of rear attachment (counterclockwise): 90°



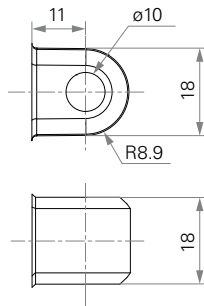
2 = Aluminum casting, hole 8, one piece casting with gear box.
Direction of rear attachment (counterclockwise): 0°



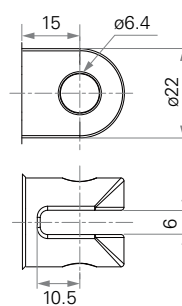
2 = Aluminum casting, hole 8, one piece casting with gear box.
Direction of rear attachment (counterclockwise): 90°



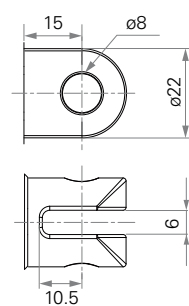
3 = Aluminum casting, hole 10, one piece casting with gear box.
Direction of rear attachment (counterclockwise): 0°



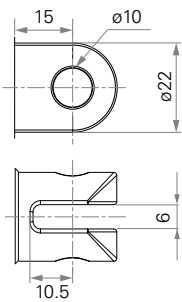
3 = Aluminum casting, hole 10, one piece casting with gear box.
Direction of rear attachment (counterclockwise): 90°



4 = Aluminum casting, clevis U, slot 6, depth 10.5, hole 6.4, one piece casting with gear box

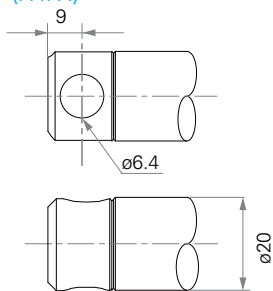


5 = Aluminum casting, clevis U, slot 6, depth 10.5, hole 8, one piece casting with gear box

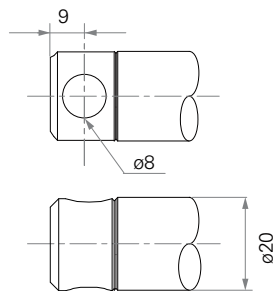


6 = Aluminum casting, clevis U, slot 6, depth 10.5, hole 10, one piece casting with gear box

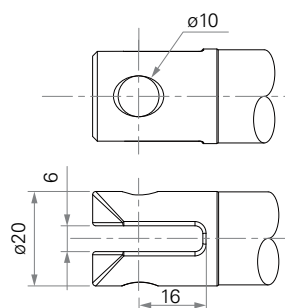
Front Attachment (mm)



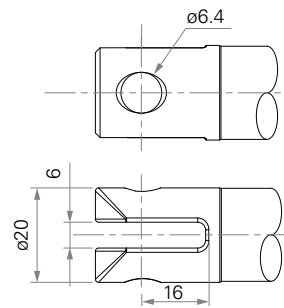
1 = Aluminum casting, no slot, hole 6.4



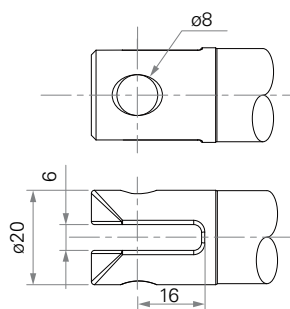
2 = Aluminum casting, no slot, hole 8



3 = Aluminum casting, U clevis, slot 6, depth 16, hole 10

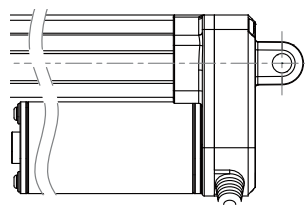


4 = Aluminum casting, U clevis, slot 6, depth 16, hole 6.4

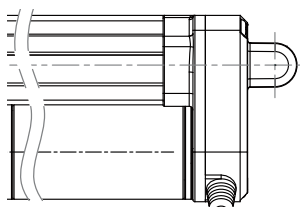


5 = Aluminum casting, U clevis, slot 6, depth 16, hole 8

Direction of Rear Attachment Counterclockwise

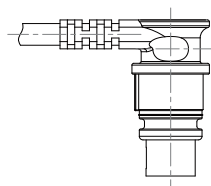


1 = 90°

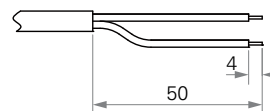


2 = 0°

Connector



1 = DIN 6P, 90° plug



2 = Tinned leads

TA2P

series



Both the TA2 and the TA2P are compact, robust, and capable of performing well in certain outdoor environments. A more powerful motor makes the TA2P capable of handling load ratings up to 3500N (787 pounds) while retaining its compact size. In addition to the high power motor, the TA2P linear actuator is available with multiple choices for feedback sensors.

Load and Speed

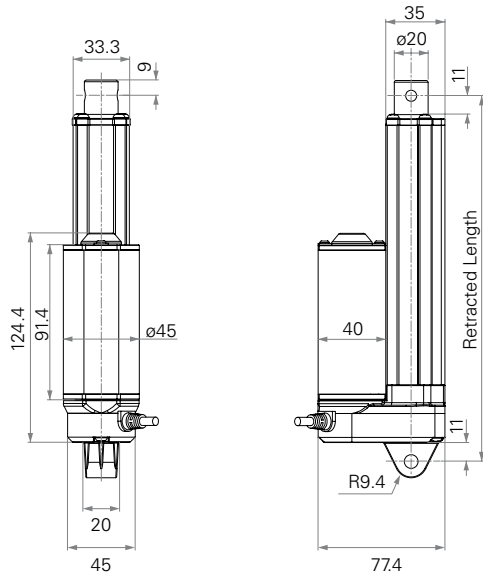
	CODE	Load (N)		Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)		Noise (db)
		Push	Pull		No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC	
Motor Speed (5200RPM)	A	250	250	250	1.2	2.3	43.0	36.0	≤ 72
	B	500	500	500	1.1	2.3	25.8	23.0	≤ 72
	C	1000	1000	1000	1.1	2.3	14.0	11.8	≤ 70
	D	1500	1500	1500	1.0	2.2	9.0	8.0	≤ 70
	E	2000	2000	2000	1.0	2.2	7.1	6.2	≤ 70
Motor Speed (6600RPM)	F	250	250	250	1.6	2.8	56.5	45.0	≤ 74
	G	500	500	500	1.5	2.8	32.5	28.5	≤ 74
	H	1000	1000	1000	1.5	2.8	16.5	14.3	≤ 72
	K	1500	1500	1500	1.3	2.8	11.1	10.0	≤ 72
	L	2000	2000	2000	1.3	2.8	8.8	7.7	≤ 72
Motor Speed (3800RPM)	S	3500	2000	3500	0.9	2.8	3.2	2.4	≤ 72
Motor Speed (2200RPM)	T	2000	2000	2000	0.3	1.2	3.2	2.4	≤ 68

NOTE

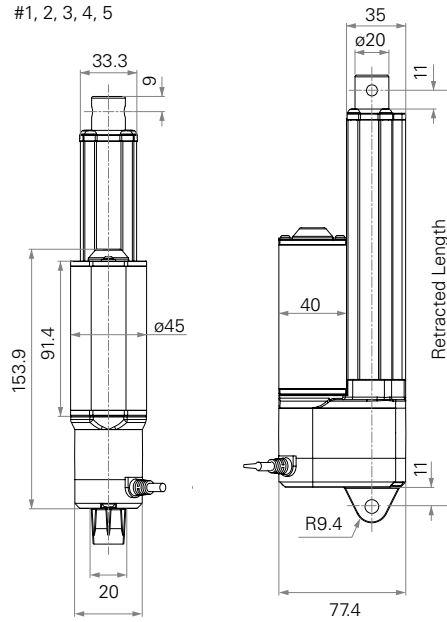
- 1 Motor 12V current is around 2 times in 24V; Motor 36V current is around 2/3 in 24V; Motor 48V current is around 1/2 in 24V; speed is around the same.
- 2 Above self lock performance needs working with Timotion control system in push direction.
- 3 Please refer to approval drawing for final value.
- 4 Environmental noise ≤ 38db.

Standard Dimension (mm)

Without
Output Signal



Output Signal
#1, 2, 3, 4, 5



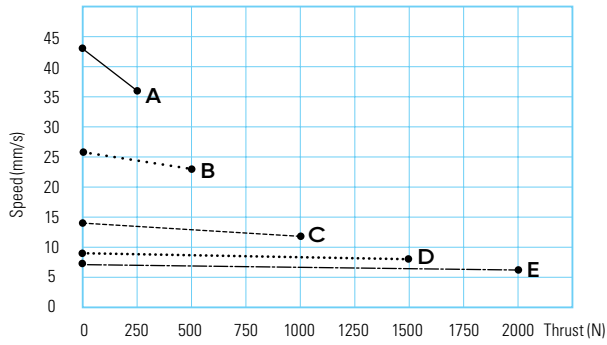
General Features

Maximum load	3,500N in push
Maximum load	2,000N in pull
Maximum speed at full load	45mm/s (with 250N in a push or pull condition)
Stroke	20~1000mm (for load s: stroke ≤ 500mm)
Minimum installation dimension	Stroke+108mm (without Hall sensor(s) or without output signals)
IP rating	Up to IP66D
Operational temperature range	-25°C~+65°C
Operational temperature range at full performance	+5°C~+45°C
Options	POT, Optical, or Hall/Reed sensor(s)

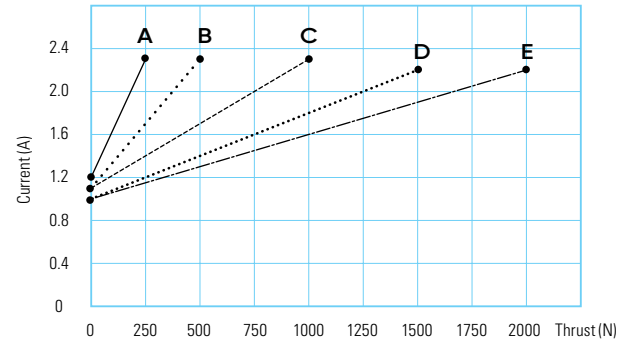
Performance Data

Motor Speed 24V 5200RPM, Duty Cycle 25%

Speed vs. Thrust

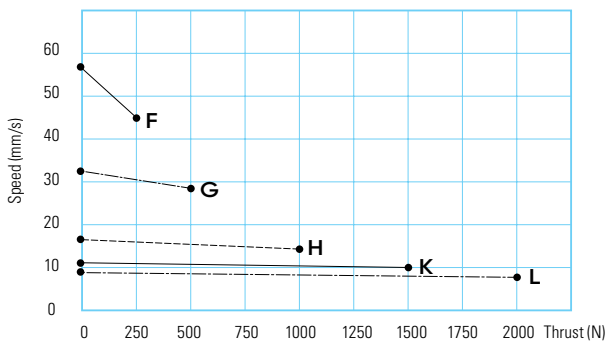


Current vs. Thrust

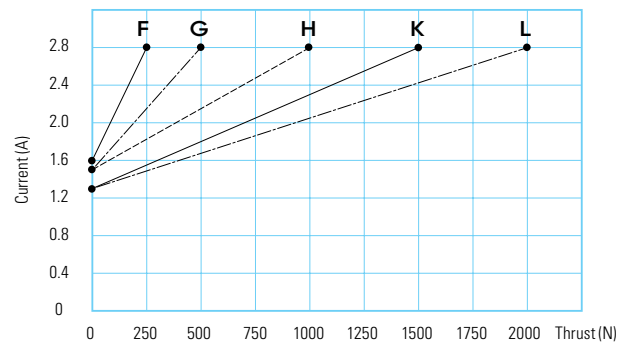


Motor Speed 24V 6600RPM, Duty Cycle 25%

Speed vs. Thrust



Current vs. Thrust



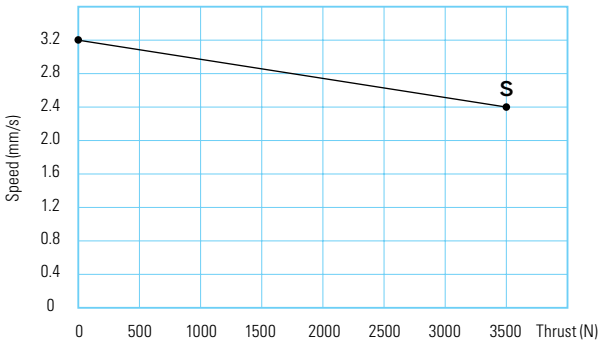
NOTE

- The performance data in the curve charts shows theoretical value.

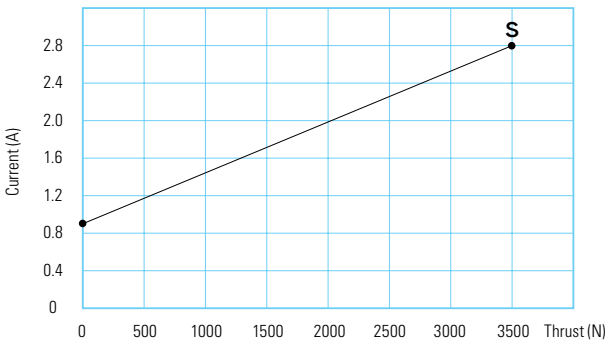
Performance Data

Motor Speed 3800RPM, Duty Cycle 25%

Speed vs. Thrust

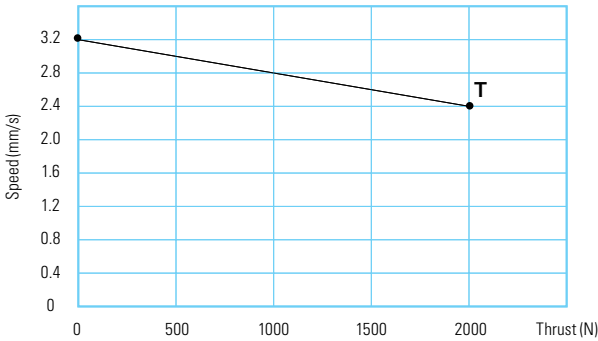


Current vs. Thrust

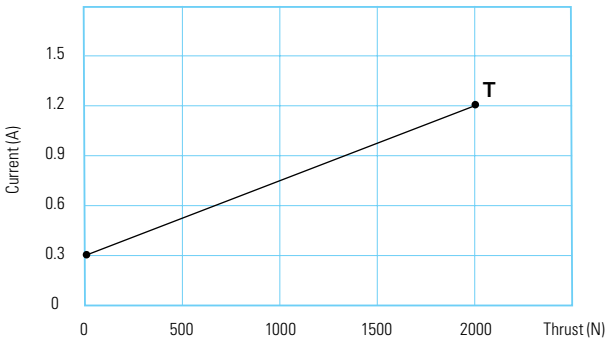


Motor Speed 2200RPM, Duty Cycle 25%

Speed vs. Thrust



Current vs. Thrust



NOTE

1 The performance data in the curve charts shows theoretical value.

TA2P Ordering Key

TA2P

Version: 20160711-L

Voltage	1 = 12V DC 2 = 24V DC	3 = 36V DC 4 = 48V DC	5 = 24V DC, PTC
Load and Speed	See page 42		
Stroke (mm)			
Restracted Length (mm)	See page 47		
Rear Attachment (mm) See page 49	1 = Aluminum casting, hole 6.4, one piece casting with gear box 2 = Aluminum casting, hole 8, one piece casting with gear box 3 = Aluminum casting, hole 10, one piece casting with gear box 4 = Aluminum casting, U clevis, slot 6, depth 10.5, hole 6.4, one piece casting with gear box 5 = Aluminum casting, U clevis, slot 6, depth 10.5, hole 8, one piece casting with gear box 6 = Aluminum casting, U clevis, slot 6, depth 10.5, hole 10, one piece casting with gear box		
Front Attachment (mm) See page 49	1 = Aluminum casting, no slot, hole 6.4 2 = Aluminum casting, no slot, hole 8 3 = Aluminum CNC, U clevis, slot 6, depth 16, hole 10 4 = Aluminum CNC, U clevis, slot 6, depth 16, hole 6.4 5 = Aluminum CNC, U clevis, slot 6, depth 16, hole 8		
Direction of Rear Attachment (Counterclockwise)	1 = 90° See page 50	2 = 0°	
Functions for Limit Switches	1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to cut current+3rd one in between to send signal 3 = Two switches at full retracted / extended positions to send signal 4 = Two switches at full retracted / extended positions to send signal+3rd one in between to send signal		
Output Signals	0 = Without 1 = POT	2 = Optical 3 = Reed sensor	4 = One Hall sensor 5 = Two Hall sensors
Connector See page 50	1 = DIN 6P, 90° plug	2 = Tinned leads	
Cable Length (mm)	1 = Straight, 300 2 = Straight, 600	3 = Straight, 1000 B~H = For direct cut system, please contact TiMOTION	
IP Rating	1 = Without	2 = IP54	3 = IP66 6 = IP66D

TA2P

Ordering Key Appendix

Retracted Length (mm)







1. Calculate $A+B+C = Y$
2. Retracted length needs to $\geq \text{Stroke}+Y$

A. Attachment	Front Attachment Code	Rear Attachment Code	
		1,2,3	4,5,6
	1	+108	+112
	2	+108	+112
	3	+120	+124
	4	+120	+124
	5	+120	+124
B. Stroke (mm)		Load (N)	Load (N)
		<3500	=3500
	0~150	-	+5
	151~200	+2	+7
	201~250	+2	+7
	251~300	+2	+7
	301~350	+12	+17
	351~400	+22	+27
C. Output Signal	Code		
	0	-	
	1	+30	
	2	+30	
	3	+30	
	4	-	
	5	-	

*For stroke over 400mm, +10mm for each increment of 50mm stroke

Functions for Limit Switches

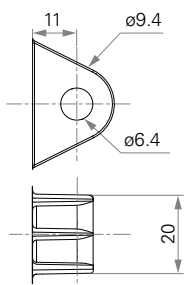
Wire Definitions

Wire Definitions			CODE			
		Pin	1	2	3	4
	Green	1	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)
	Red	2	N/A	N/A	Common	Common
	White	3	N/A	Middle switch pinB	Upper limit switch	Upper limit switch
	Black	4	N/A	Middle switch pinA	N/A	Medium limit switch
	Yellow	5	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)
	Blue	6	N/A	N/A	Lower limit switch	Lower limit switch

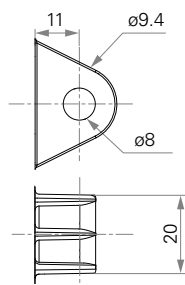
NOTE

² See ordering key - functions for limit switches.

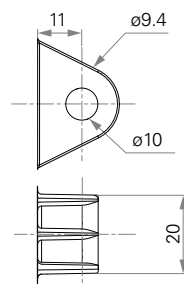
Rear Attachment (mm)



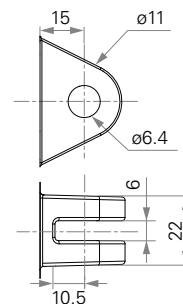
1 = Aluminum casting, hole 6.4, one piece casting with gear box



2 = Aluminum casting, hole 8, one piece casting with gear box

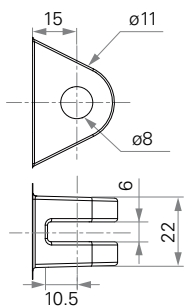


3 = Aluminum casting, hole 10, one piece casting with gear box

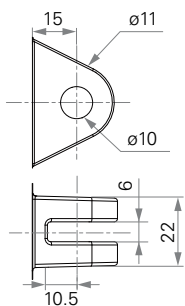


4 = Aluminum casting, clevis U, slot 6, depth 10.5, hole 6.4, one piece casting with gear box

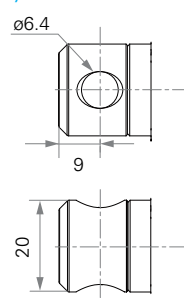
Front Attachment (mm)



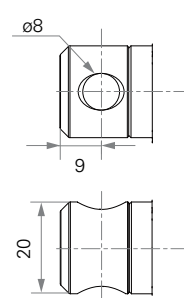
5 = Aluminum casting, clevis U, slot 6, depth 10.5, hole 8, one piece casting with gear box



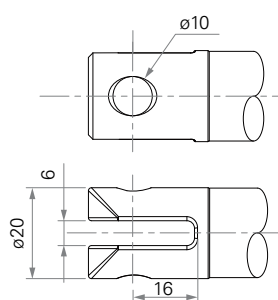
6 = Aluminum casting, clevis U, slot 6, depth 10.5, hole 10, one piece casting with gear box



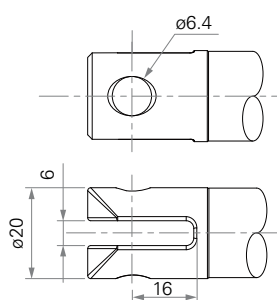
1 = Aluminum casting, no slot, hole 6.4



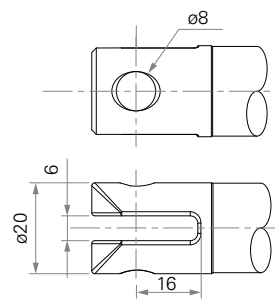
2 = Aluminum casting, no slot, hole 8



3 = Aluminum CNC, U clevis, slot 6, depth 16, hole 10



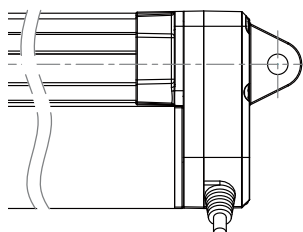
4 = Aluminum CNC, U clevis, slot 6, depth 16, hole 6.4



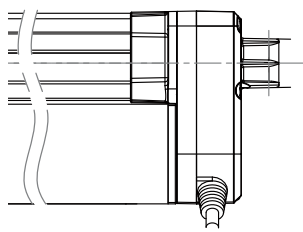
5 = Aluminum CNC, U clevis, slot 6, depth 16, hole 8

Direction of Rear Attachment Counterclockwise

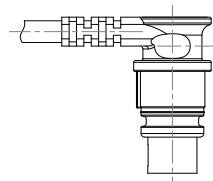
Connector



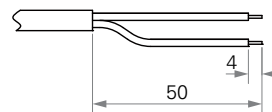
1 = 90°



2 = 0°



1 = DIN 6P, 90° plug



2 = Tinned leads



TA16

series



TiMOTION's TA16 series linear actuator is similar to the TA2 linear actuator, but is specifically designed for low-noise medical applications where a compact linear actuator is needed. It is available with optional IP66 protection and Hall sensors for position feedback.

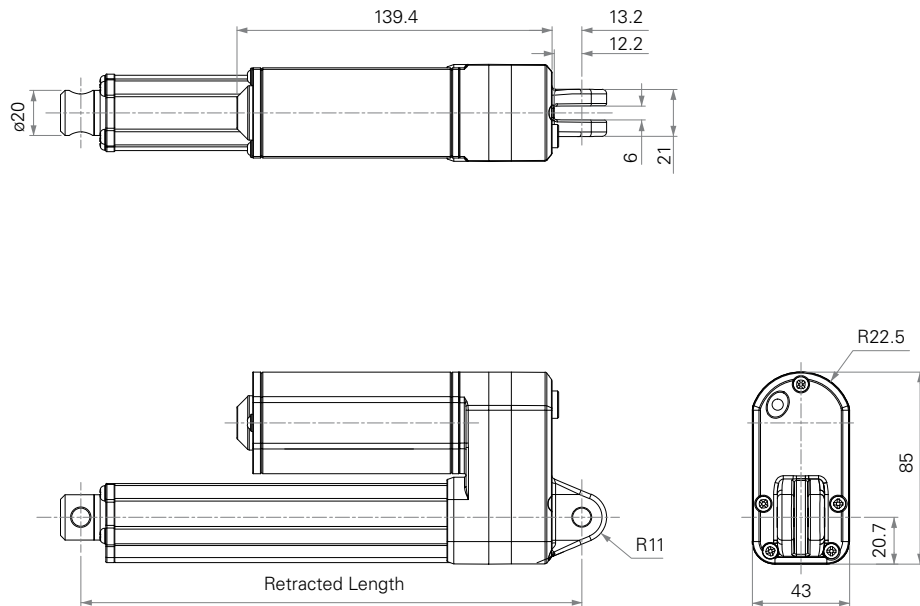
Load and Speed

CODE		Load (N)		Typical Current (A)		Typical Speed (mm/s)	
		Push	Pull	No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (3800RPM)	A	2500	2500	0.9	2.8	5.2	3.0
	B	2000	2000	0.9	2.8	8.3	4.7
	C	1500	1500	0.9	2.8	11.9	7.0
	D	1000	1000	1.0	2.8	17.7	10.3
Motor Speed (5600RPM)	G	3500	3500	1.5	4.7	12.0	6.5
	J	2000	2000	1.5	3.2	17.0	10.5
	K	1500	1500	1.5	3.5	23.5	13.5

NOTE

- 1 With a 12V motor, the current is approximately twice the current measured in 24V. With a 36V motor, the current is approximately two-thirds the current measured in 24V; speed will be similar for both voltages.
- 2 Above self lock performance needs working with TiMOTION control system.

Standard Dimension (mm)



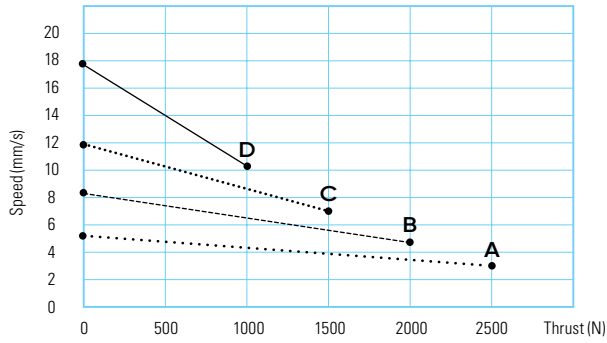
General Features

Maximum load	3,500N in push and pull
Maximum speed at full load	13.5 mm/s (with 1500N in a push or pull condition)
Stroke	20~1000mm
Minimum installation dimension	Stroke+112mm (without output signals)
IP rating	Up to IP66
Operational temperature range	+5°C~+45°C
Options	Hall sensor(s)
With very low noise, small size for easy installation	

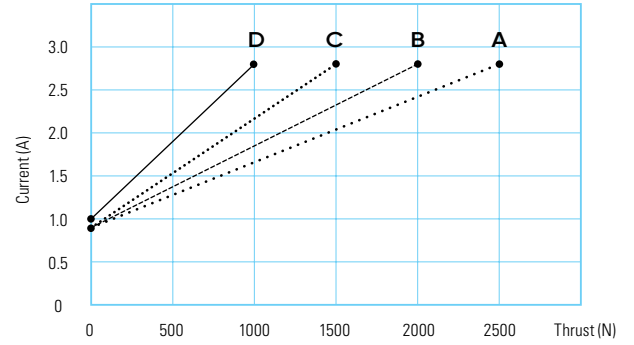
Performance Data

Motor Speed 3800RPM, Duty Cycle 10%

Speed vs. Thrust

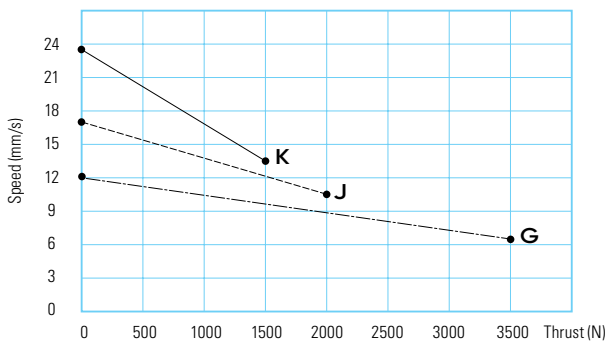


Current vs. Thrust

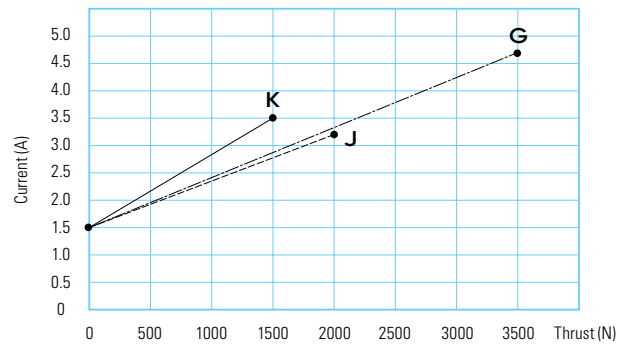


Motor Speed 5600RPM, Duty Cycle 10%

Speed vs. Thrust



Current vs. Thrust



NOTE

- The performance data in the curve charts shows theoretical value.

TA16 Ordering Key

TA16

Version: 20160506-G

Voltage	1 = 12V DC	2 = 24V DC		
Load and Speed	See page 52			
Stroke (mm)				
Restracted Lengh (mm)	See page 56			
Rear Attachment (mm) See page 58	1 = Aluminum casting, U clevis, width 6, depth 12.2, hole 6.4, one piece casting with gear box 2 = Aluminum casting, U clevis, width 6, depth 12.2, hole 8, one piece casting with gear box 3 = Aluminum casting, U clevis, width 6, depth 12.2, hole 10, one piece casting with gear box			
Front Attachment (mm) See page 58	1 = Aluminum casting, no slot, hole 6.4 2 = Aluminum casting, no slot, hole 8 3 = Aluminum casting, no slot, hole 10 4 = Aluminum casting, U clevis, width 6, depth 13, hole 6.4 5 = Aluminum casting, U clevis, width 6, depth 13, hole 8 6 = Aluminum casting, U clevis, width 6, depth 13, hole 10			
Direction of Rear Attachment (Counterclockwise)	1 = 90°	2 = 0°	See page 58	
IP Rating	1 = Without	2 = IP54	3 = IP66	
Functions for Limit Switches	1 = Two switches at full retracted/extended positions to cut current 2 = Two switches at full retracted/extended positions to cut current + 3rd LS to send signal 3 = Two switches at full retracted/extended positions to send signal 4 = Two switches at full retracted/extended positions to send signal + 3rd LS to send signal			
Special Functions for Spindle Sub-Assembly	0 = Without	2 = Standard push only		
Output Signals	0 = Without	1 = POT	4 = One Hall sensor	5 = Two Hall sensors
Connector See page 59	1 = DIN 6P, 90° plug 2 = Tinned leads 4 = Big 01P, plug C = Y cable (For direct cut system, water proof, anti pull)		E = MOLEX 8P, plug F = DIN 6P, 180° plug G = Audio plug	
Cable Length (mm)	0 = Straight, 100	4 = Straight, 1250	8 = Curly, 400	
	1 = Straight, 500	5 = Straight, 1500	B~H = For direct cut system, please contact TIMOTION	
	2 = Straight, 750	6 = Straight, 2000		
	3 = Straight, 1000	7 = Curly, 200		

TA16

Ordering Key Appendix

Retracted Length (mm)







1. Calculate $A+B+C = Y$
2. Retracted length needs to $\geq \text{Stroke}+Y$

A. Attachment	Front Attachment Code		Rear Attachment Code	
			1,2,3	
	1,2,3		+112	
	4,5,6		+122	
B. Stroke (mm)	Load (N)		Load (N)	
	<3500		=3500	
	~150		-	
	~150		+5	
	151~200		+8	
	201~250		+8	
	251~300		+13	
	301~350		+13	
	351~400		+18	
C. Spindle Sub	Safty Nut/ Push Only		A,B	
	0,2		-	
	1,3		+10	
D. Output Signal	Code			
	0,4,5		-	
	1		+36	

*For stroke over 400mm, +5mm for each incremental of 50mm stroke.

Functions for Limit Switches

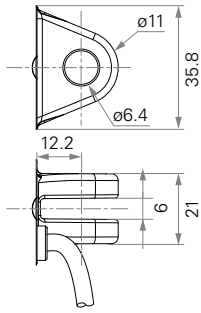
Wire Definitions

Wire Definitions			CODE			
		Pin	1	2	3	4
	Green	1	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)	Extend (VDC+)
	Red	2	N/A	N/A	Common	Common
	White	3	N/A	Middle switch pinB	Upper limit switch	Upper limit switch
	Black	4	N/A	Middle switch pinA	N/A	Medium limit switch
	Yellow	5	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)	Retract (VDC+)
	Blue	6	N/A	N/A	Lower limit switch	Lower limit switch

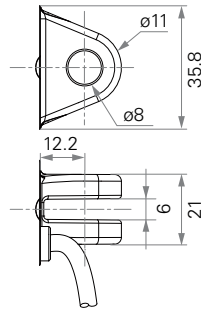
NOTE

¹ See ordering key - functions for limit switches.

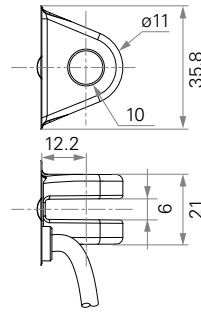
Rear Attachment (mm)



1 = Aluminum casting, U clevis, width 6, depth 12.2, hole 6.4, one piece casting with gear box

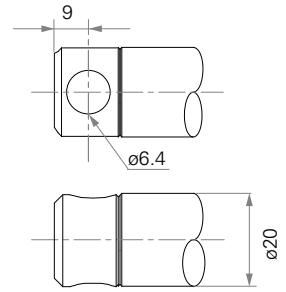


2 = Aluminum casting, U clevis, width 6, depth 12.2, hole 8, one piece casting with gear box

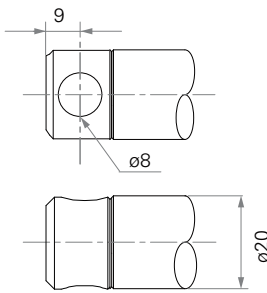


3 = Aluminum casting, U clevis, width 6, depth 12.2, hole 10, one piece casting with gear box

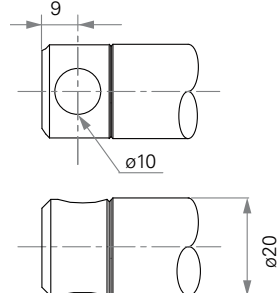
Front Attachment (mm)



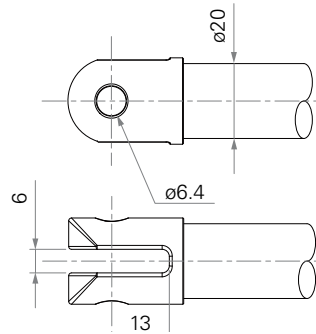
1 = Aluminum casting, no slot, hole 6.4



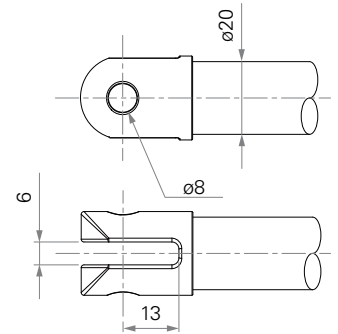
2 = Aluminum casting, no slot, hole 8



3 = Aluminum casting, no slot, hole 10

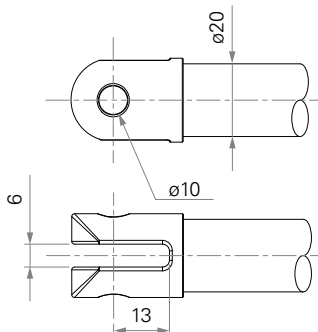


4 = Aluminum casting, U clevis, width 6, depth 13, hole 6.4

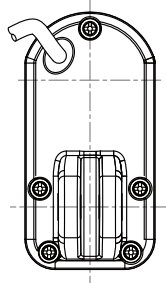


5 = Aluminum casting, U clevis, width 6, depth 13, hole 8

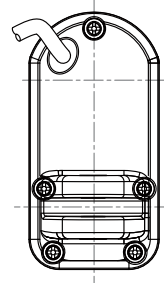
Direction of Rear Attachment Counterclockwise



6 = Aluminum casting, U clevis, width 6, depth 13, hole 10

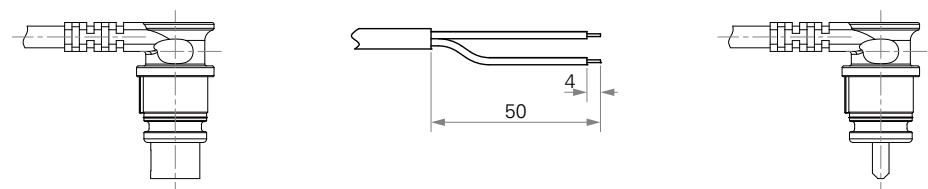


1 = 90°

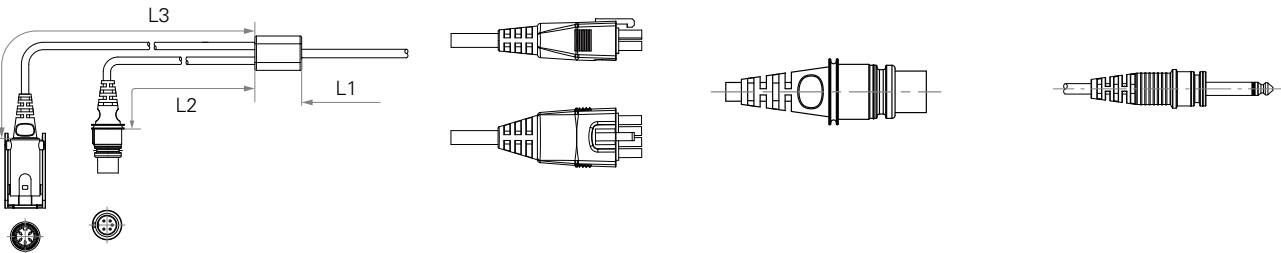


2 = 0°

Connector



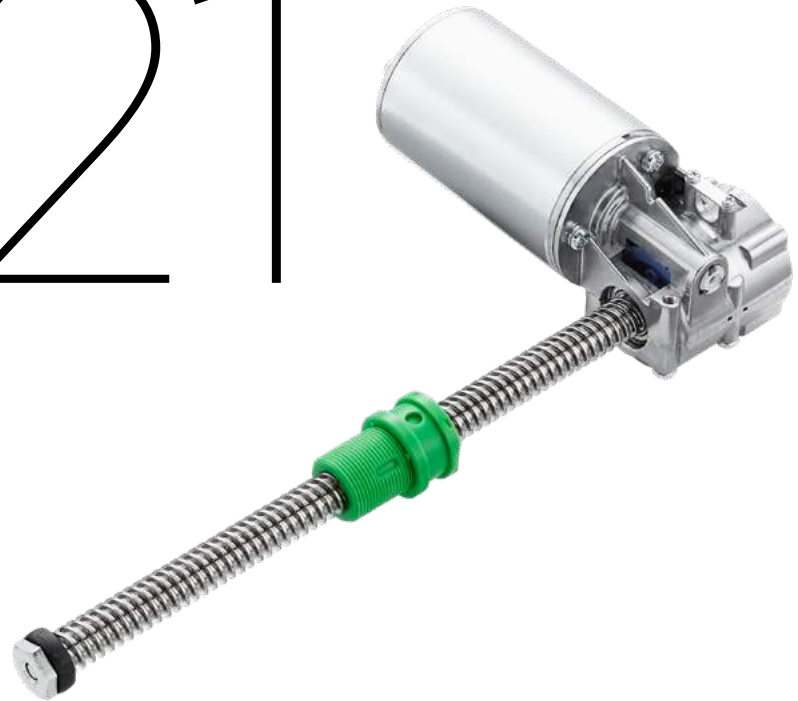
1 = DIN 6P, 90° plug 2 = Tinned leads 4 = Big 01P, plug



C = Y cable (For direct cut system,water proof, anti pull) E = MOLEX 8P, plug F = DIN 6P, 180° plug G = Audio plug

TA21

series



TiMOTION's TA21 electric linear actuator was designed for use in height adjustable medical and industrial workstations. Customers have a high degree of design flexibility with this actuator as it does not include a standard outer tube. This allows manufacturers to decide on the exact aesthetic and ingress specifications for their electric lifting column and overall application

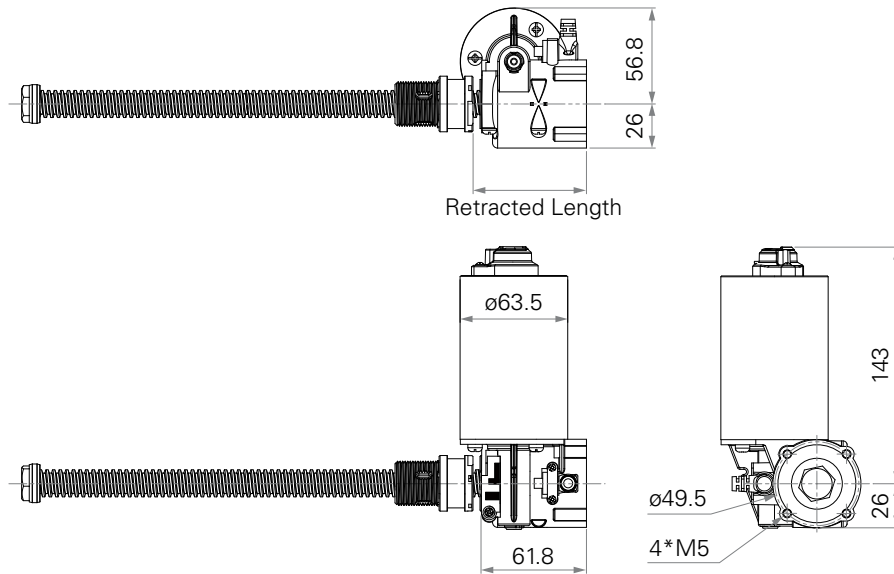
Load and Speed

CODE		Load (N)		Typical Current (A)		Typical Speed (mm/s)	
		Push	Pull	No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (3800RPM)	A	10000	6000	2.0	15.0	16.1	6.3
	C	7000	6000	2.0	9.0	16.4	8.3
	D	4000	4000	2.0	9.5	32.9	16.2

NOTE

1 Self locking force: Tested average value when working with TiMOTION control system.

Standard Dimension (mm)



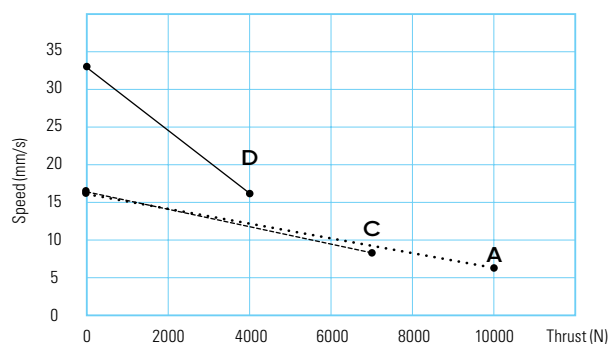
General Features

Voltage of motor	24V DC
Maximum load	10,000N in push
Maximum load	6,000N in pull
Maximum speed at full load	16.2mm/s (with 4000N in a push or pull condition)
Motor Cable Color	Black or grey

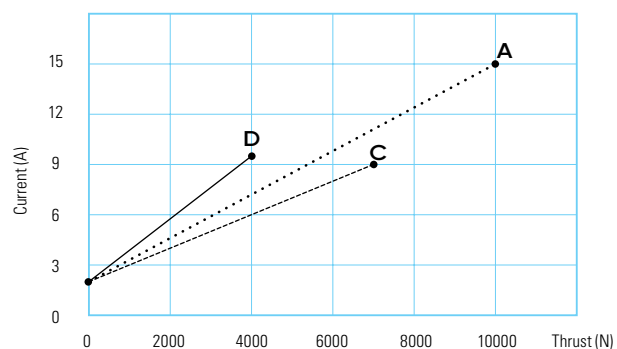
Performance Data

Motor Speed 24V 3800RPM, Duty Cycle 10%

Speed vs. Thrust



Current vs. Thrust



NOTE

1 The performance data in the curve charts shows theoretical value.

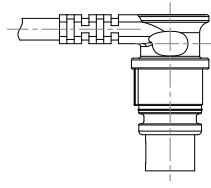
TA21 Ordering Key

TA21

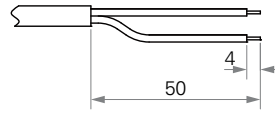
Version: 20160805-A

Voltage	2 = 24V DC		
Load and Speed	See page 60		
Stroke (mm)			
Restracted Lengh (mm)	See page 61		
Motor Cable Color	1 = Black	2 = Grey (Pantone 428C)	
Special Functions for Spindle Sub-Assembly	1 = Safety nut		
Signal Output	0 = Without	2 = Two Hall sensors	3 = Reed sensor
Connector See page 64	1 = DIN 6P, 90° plug	2 = Tinned Leads	F = DIN 6P, 180° plug
Cable Length (mm)	1= Straight, 500 2= Straight, 750 3= Straight, 1000	4= Straight, 1250 5= Straight, 1500 6= Straight, 2000	7= Curly, 200 8= Curly, 400

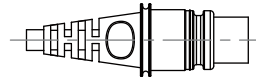
Connector



1 = DIN 6P, 90° plug



2 = Tinned leads



F = DIN 6P, 180° plug



TGM1

series

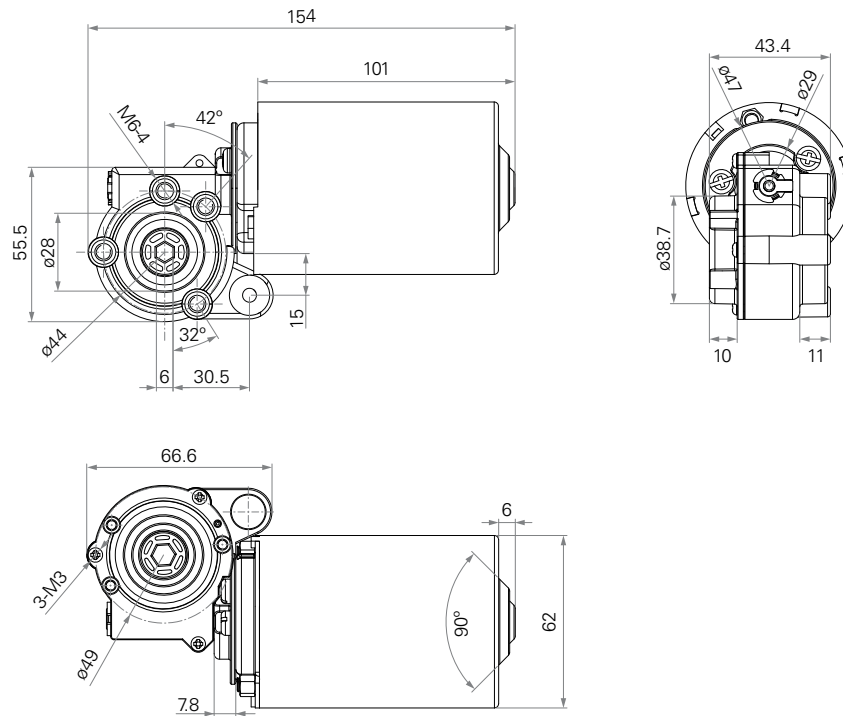


TiMOTION's TGM1 series gear motor was designed primarily for ergonomic applications like height adjustable workstations and tables, but can be used in many other applications. This economical product allows for fast, smooth and quiet adjustment of built-in spindles through the use of external limit switches. Shafting allows for the mechanical synchronization of dual spindles.

Load and Speed

	CODE	Rated Torque (Nm)	Self Locking Force (Nm)		Typical Current (A)		Typical Speed (RPM±5%)	
			Brake #0	Brake #1	No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (3800RPM)	A	7.6	1.4	4.4	1.0	5.0	132	72
	D	3.8	0.2	1.9	1.0	5.0	264	144
Motor Speed (3400RPM)	B	7.7	1.4	4.4	1.0	4.0	112	64
	E	3.9	0.2	1.9	1.0	4.0	224	128
Motor Speed (2600RPM)	C	6.8	1.4	4.4	1.0	3.0	88	51
	F	3.4	0.2	1.9	1.0	3.0	175	102

Standard Dimension (mm)



General Features

Voltage of motor	24V DC or 24V DC (UL)
Maximum speed at full load	144RPM ($\pm 5\%$) after gear reduction
Maximum rated torque	7.7Nm
Operational temperature range at full performance	+5°C~+45°C
Options	Hall sensor(s)
Hexagon hole for the shaft by 6mm diameter	
Low noise	

TGM1 Ordering Key

TGM1

Version: 20170520-H

Voltage	2 = 24V DC	5 = 24V DC, PTC	
Load and Speed	See page 66		
Output Signal	0 = Without	1 = One Hall sensor	2 = Two Hall sensors
Brake	0 = Without	1 = Motor brake	
Connector	0 = Tinned leads	1 = DIN 6P, 90° plug	2 = MOLEX 8P, plug
Cable Length (mm)	0 = Straight, 1000 1 = Straight, 1500	2 = Straight, 2000 3 = Curly, 1000	
External Limit Switches (TES2)	00 = Without	XX = Number of output rotations (between 13~17 & 25~35 rotations, factory preset)	

TGM2

series



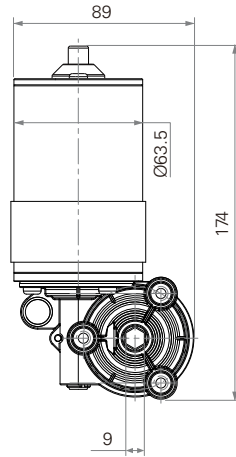
The TGM2 series is TiMOTION's most powerful gear motor. It was designed primarily for ergonomic applications like height adjustable workstations and tables, but can be used in many other applications. This economical product allows for fast, smooth and quiet adjustment of built-in spindles through the use of external limit switches. Shafting allows for the mechanical synchronization of dual spindles.

Load and Speed

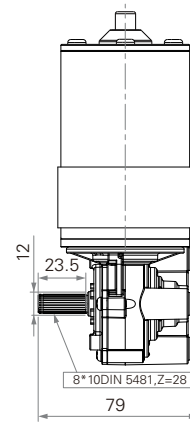
	CODE	Rated Torque (Nm)	Self Locking Force (Nm)		Typical Current (A)		Typical Speed (RPM±5%)	
			Brake #0	Brake #1	No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (3800RPM)	A	16.0	5	11	1.5	8.5	110	49
Motor Speed (2200RPM)	B	13.4	5	11	1.5	4.0	62	31

Standard Dimension (mm)

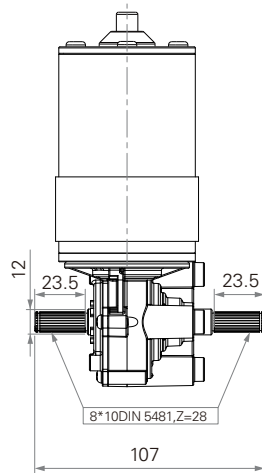
Shaft Selection1
Drive shaft hole
(inner hexagon 9mm)



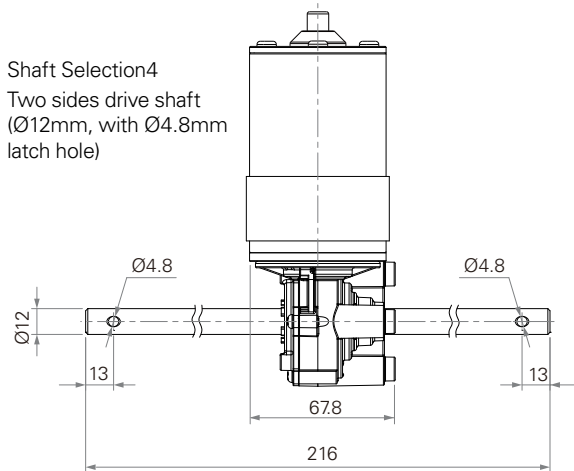
Shaft Selection2
One side drive shaft
(Ø12mm, knurling)



Shaft Selection3
Two sides drive shaft
(Ø12mm, knurling)



Shaft Selection4
Two sides drive shaft
(Ø12mm, with Ø4.8mm
latch hole)



General Features

Voltage of motor	24V DC
Maximum speed at full load	49RPM (±5%) after gear reduction
Maximum rated torque	16Nm
Operational temperature range at full performance	+5°C~+45°C
Options	Hall sensor(s)
Hexagon hole for the shaft by 9mm diameter	
Low noise	

TGM2 Ordering Key

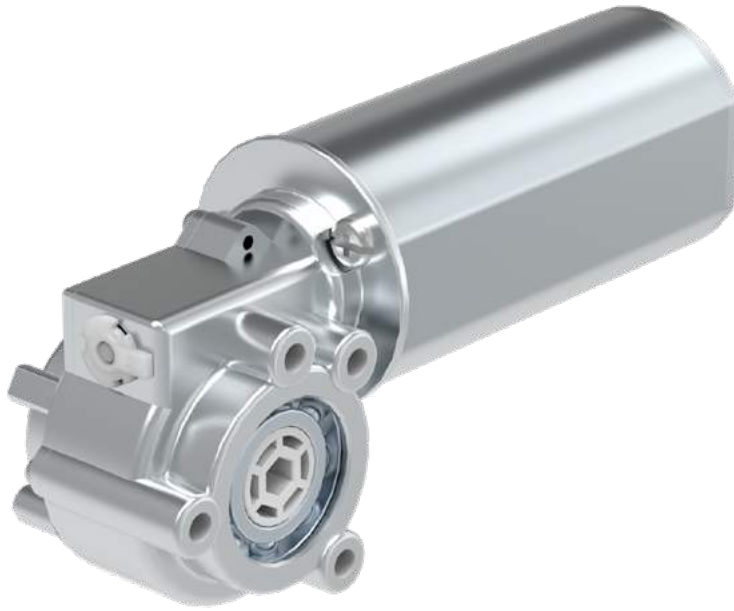
TGM2

Version: 20170520-H

Voltage	5 = 24V DC, thermal protector			
Load and Speed	See page 69			
Output Signal	0 = Without	1 = One Hall sensor	2 = Two Hall sensors	
Brake	0 = Without	1 = Motor brake		
Connector	0 = Tinned leads	1 = DIN 6P, 90° plug	2 = MOLEX 8P, plug	
Cable Length (mm)	0 = Straight, 1000	1 = Straight, 1500	2 = Straight, 2000	3 = Curly, 1000
Torgue Output	1 = Drive shaft hole (Inner hexagon 9mm) 2 = One side drive shaft (Ø12mm, knurling) 3 = Two sides drive shaft (Ø12mm, knurling)		4 = Two sides drive shaft (Ø12mm, with Ø4.8 latch hole)	
External Limit Switches (TES2)	00 = Without	XX = Number of output rotations (Between13~17 & 25~35 rotations, factory preset)		

TGM3

series



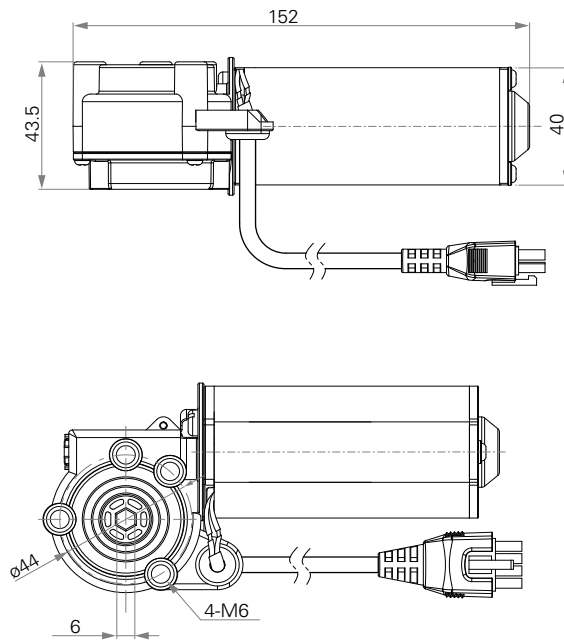
The TGM3 series is TiMOTION's compact size gear motor. It was designed primarily for ergonomic applications like height adjustable workstations and tables, but can be used in many other applications. This economical product allows for fast, smooth and quiet adjustment of built-in spindles through the use of external limit switches. Shafting allows for the mechanical synchronization of dual spindles.

Load and Speed

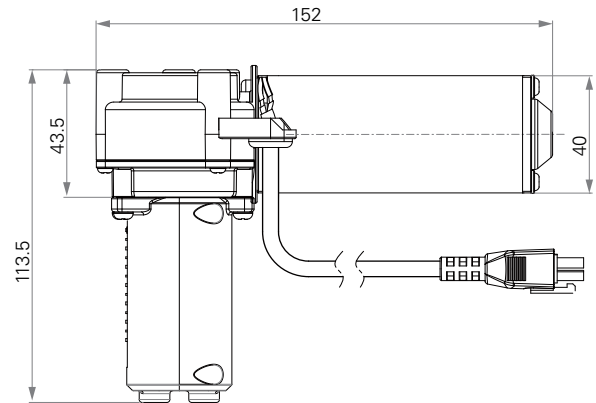
CODE		Rated Torque (Nm)	Self Locking Force (N)	Typical Current (A)		Typical Speed (RPM \pm 5%)	
				No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (3800RPM)	A	4.6	1.7	1.0	3.2	132	52
	C	2.3	0.2	1.0	3.2	264	105
Motor Speed (2200RPM)	B	3.7	1.7	0.8	1.6	79	26
	D	1.9	0.2	0.8	1.6	157	52

Standard Dimension (mm)

Without TES2



With TES2



General Features

Voltage of motor	24V DC
Maximum speed	105RPM ($\pm 5\%$) after gear reduction
Maximum rated Torque	4.6Nm after gear reduction
Operational temperature range at full performance	+5°C~+45°C
Options	Hall sensor(s)
Hexagon hole for the shaft by 6mm diameter	
Low noise	

TGM3 Ordering Key

TGM3

Version: 20171109-H

Voltage	2 = 24V DC			
Load and Speed	See page 72			
Output Signal	0 = Without	1 = One Hall sensor	2 = Two Hall sensors	
Motor Brake	0 = Without			
Connector	0 = Tinned leads	1 = DIN 6P, 90° plug	2 = MOLEX 8P, plug	
Cable Length (mm)	0 = Straight, 1000	1 = Straight, 1500	2 = Straight, 2000	3 = Curly, 1000
Bracket	0 = Without			
External Limit Switches (TES2)	0 = Without	1 = With		
Output Rotation (If with TES2)	00 = Without	XX = Number of hexagon rotations (Between 13~17turns & 25~35 turns.)		

TGM4

series

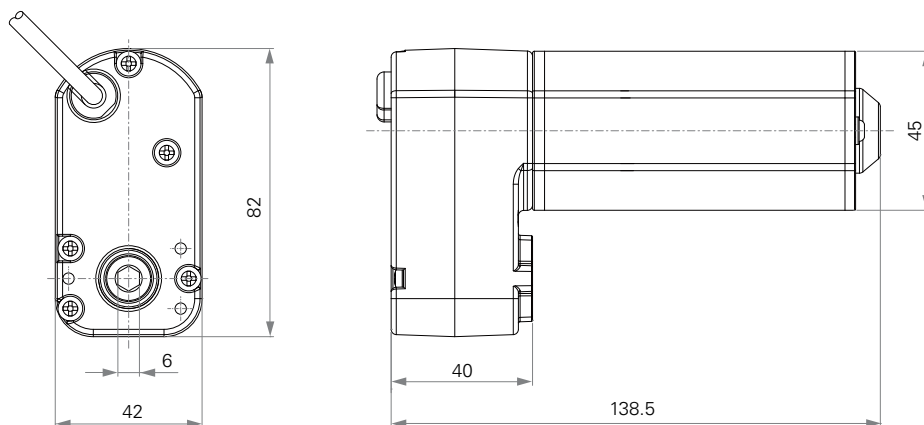


The TGM4 series is TiMOTION's compact size gear motor. It was designed primarily for ergonomic applications like height adjustable workstations and tables, but can be used in many other applications. This economical product allows for fast, smooth and quiet adjustment of built-in spindles through the use of external limit switches. Shafting allows for the mechanical synchronization of dual spindles.

Load and Speed

	CODE	Rated Torque (Nm)	Self Locking Force (Nm)		Typical Current (A)		Typical Speed (RPM±5%)	
			Brake #0	Brake #1	No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (3800RPM)	A	3.9	1.4	2.4	1.0	3.2	158.5	75.5
Motor Speed (2200RPM)	B	3.1	1.4	2.4	1.0	1.6	94.0	30.0
Motor Speed (4100RPM)	C	4.1	1.4	2.4	1.0	3.5	168.0	67.0
Motor Speed (3300RPM)	D	2.2	1.4	2.4	1.0	2.0	137.0	76.0

Standard Dimension (mm)



General Features

Voltage of motor	24V DC
Maximum speed at full load	76RPM ($\pm 5\%$) after gear reduction
Maximum rated torque	4.1Nm
Operational temperature range at full performance	+5°C~+45°C
Options	Hall sensor(s)
Hexagon hole for the shaft by 6mm diameter	
Low noise	

TGM4 Ordering Key

TGM4

Version: 20170520-H

Voltage	2 = 24V DC			
Load and Speed	See page 75			
Output Signal	0 = Without	1 = One Hall sensor	2 = Two Hall sensors	
Brake	0 = Without	1 = Motor brake		
Connector	0 = Tinned leads	1 = DIN 6P, 90° plug	2 = MOLEX 8P, plug	
Cable Length (mm)	0 = Straight, 1000	1 = Straight, 1500	2 = Straight, 2000	3 = Curly, 1000
External Limit Switches (TES2)	00 = Without	XX = Number of output rotations (between13~17 & 25~35 rotations, factory preset)		

TGM7

series

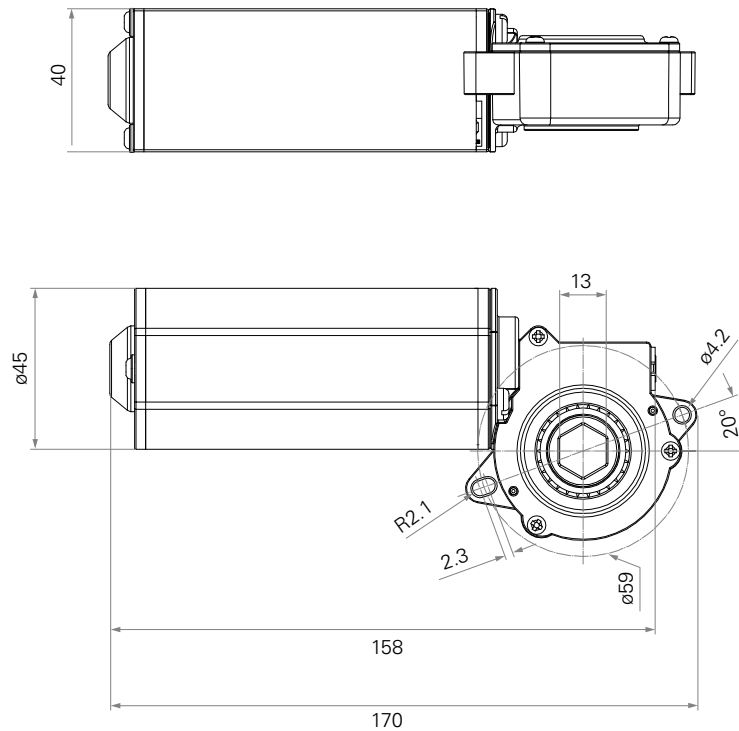


The TGM7 series is TiMOTION's compact size gear motor. It was designed primarily for ergonomic applications like height adjustable workstations and tables, but can be used in many other applications. This economical product allows for fast, smooth and quiet adjustment of built-in spindles through the use of external limit switches. Shafting allows for the mechanical synchronization of dual spindles.

Load and Speed

	CODE	Rated Torque (Nm)	Self Locking Force (Nm)		Typical Current (A)		Typical Speed (RPM±5%)	
			Brake #0	Brake #1	No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (5200RPM)	C	7.2	0.9	2.9	1.0	6.0	177	78
	D	3.6	0.2	0.7	1.0	6.0	355	156

Standard Dimension (mm)



General Features

Voltage of motor	24V DC
Maximum speed at full load	156RPM ($\pm 5\%$) after gear reduction
Maximum rated torque	7.2Nm
Operational temperature range at full performance	+5°C~+45°C
Options	Hall sensor(s)
Low noise	

TGM7 Ordering Key

TGM7

Version: 20170520-C

Voltage	2 = 24V DC			
Load and Speed	See page 78			
Output Signal	0 = Without	1 = One Hall sensor	2 = Two Hall sensors	
Brake	0 = Without	1 = Motor brake		
Connector	0 = Tinned leads	1 = DIN 6P, 90° plug	2 = MOLEX 8P, plug	
Cable Length (mm)	0 = Straight, 1000	1 = Straight, 1500	2 = Straight, 2000	3 = Curly, 1000



TL3

series



The TL3 columns from TiMOTION are made up of three extruded aluminum tubes of rectangular shape that give the system great stability and a high stroke with reduced retracted length. This electric lifting column allows for an easy integration into many height adjustable applications.

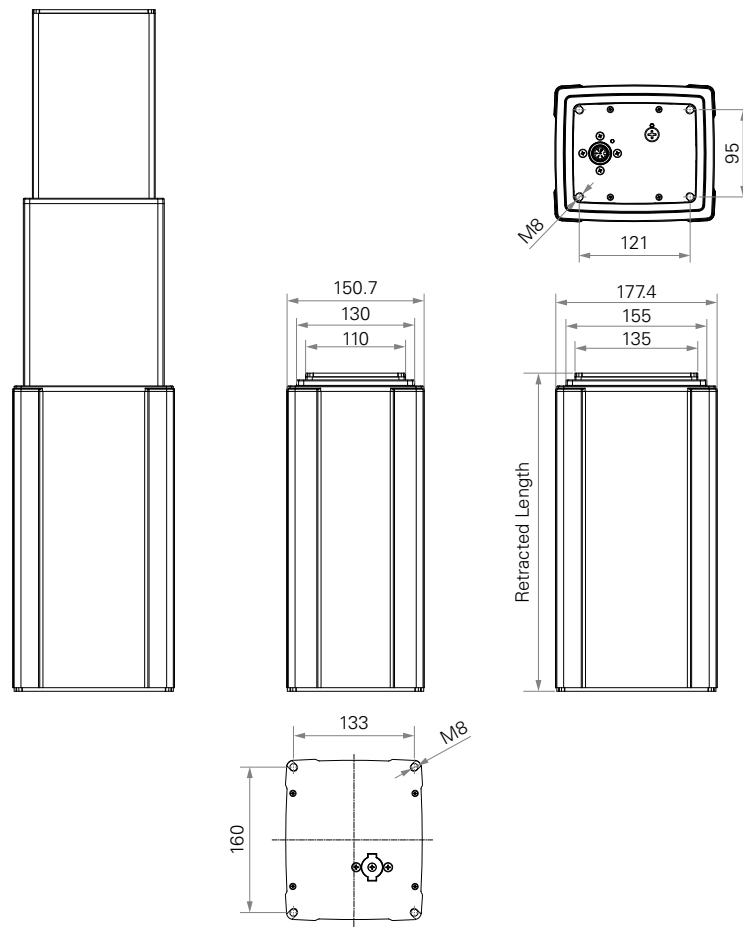
Load and Speed

	CODE	Load (N)	Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)	
				No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
		Push					
Motor Speed (2200RPM)	B	4000	4000	2.5	6.3	14.5	7.6
	C	2000	2000	2.5	4.3	22.0	13.0
	D	1000	1000	2.5	3.8	39.0	24.0
Motor Speed (2800RPM)	E	4000	4000	3.5	7.5	18.5	9.4
	F	2000	2000	3.5	6.3	35.0	20.0
Motor Speed (3400RPM)	G	4000	4000	4.0	12.0	31.0	15.0

NOTE

¹ With a 12V motor, the current is approximately twice the current measured in 24V; speed will be similar for both voltages.

Standard Dimension (mm)



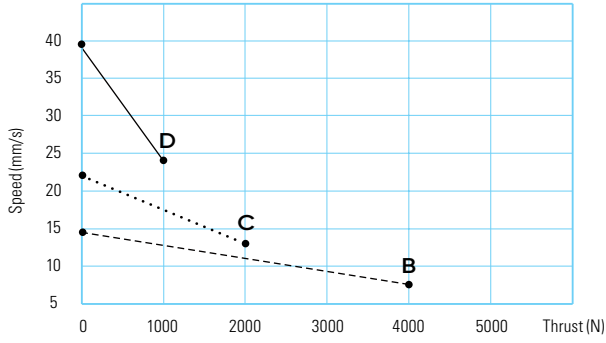
General Features

Maximum load	4,000N in push
Maximum dynamic bending moment	1,000Nm
Maximum static bending moment	2,000Nm
Maximum speed at full load	24mm/s (with 1,000N in a push condition)
Minimum installation dimension	Stroke/2+150mm (If max. load= 1,000 / 2,000N)
Dimension of cross section	177.4x150.7 mm
Stroke	100~1200mm
Operational temperature range	+5°C~+45°C
Options	POT, Hall sensor(s)

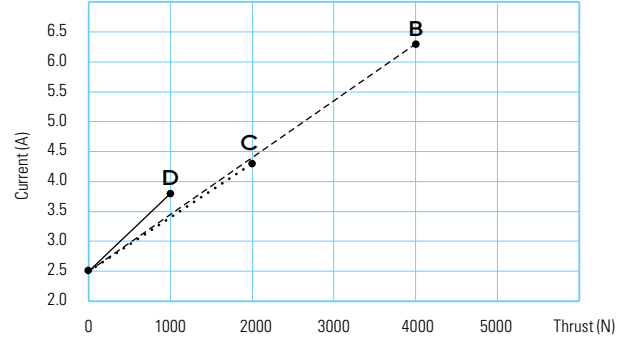
Performance Data

Motor Speed 24V 2200RPM, Duty Cycle 10%

Speed vs. Thrust

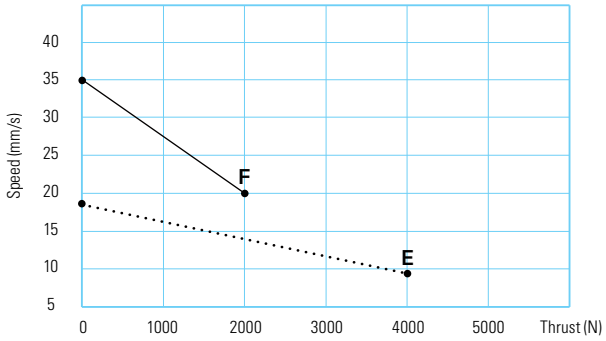


Current vs. Thrust

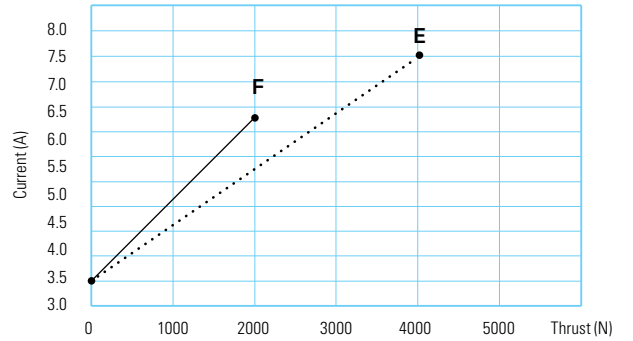


Motor Speed 24V 2800RPM, Duty Cycle 10%

Speed vs. Thrust

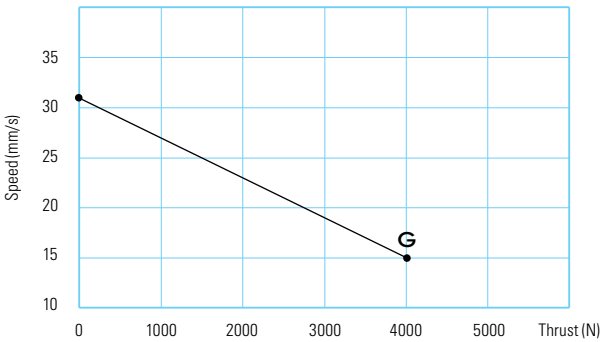


Current vs. Thrust

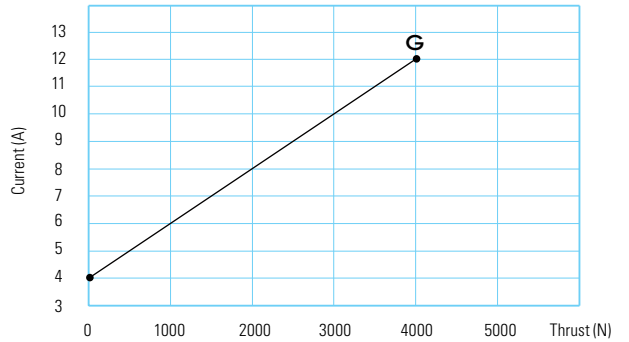


Motor Speed 24V 3400RPM, Duty Cycle 10%

Speed vs. Thrust



Current vs. Thrust



NOTE

- The performance data in the curve charts shows theoretical value.

TL3 Top End Socket Ordering Key

TL3

Version: 20170613-J

Voltage	1 = 12V DC	5 = 24V DC, thermal protector
Load and Speed	See page 82	
Stroke (mm)	100-1200	
Restracted Lenght (mm)	See page 88	
Cable Exit See page 90	1 = Top end socket	
Special Functions for Spindle Sub-Assembly	0 = Without (standard)	
Functions for Limit Switches See page 89	1 = Two switches at full retracted / extended positions to cut current 3 = Two switches at full retracted / extended positions to send signal	
IP Rating	1 = Without	2 = IPX4 3 = IPX6
Output Signals	0 = Without	2 = Two Hall sensors 3 = POT
Connector See page 90	1 = DIN 6P, socket	
Cable Length (mm)	0 = Without (the corresponding extension cable TEC needs to be ordered seperately)	

NOTE

1 TL3 is designed especially for push applications, not suitable for pull.

TL3 Side Cable Ordering Key

TL3

Version: 20170613-J

Voltage	1 = 12VDC	5 = 24V DC, thermal protector	
Load and Speed	See page 82		
Stroke (mm)	100-1200		
Restracted Lengh (mm)	See page 88		
Cable Exit See page 90	2 = Bottom side cable 3 = Top side cable		
Special Functions for Spindle Sub-Assembly	0 = Without (standard)		
Functions for Limit Switches See page 89	1 = Two switches at full retracted/ extended positions to cut current 3 = Two switches at full retracted/ extended positions to send signal		
IP Rating	1 = Without	2 = IPX4	3 = IPX6
Output Signals	0 = Without	2 = Two Hall sensors	3 = POT
Connector See page 90	1 = DIN 6P, 90° plug	2 = Tinned leads	F = DIN 6P, 180° socket
Cable Length (mm)	1 = Straight, 500 2 = Straight, 750	3 = Straight, 1000 4 = Straight, 1250	5 = Straight, 1500 6 = Straight, 1750

NOTE

1 TL3 is designed especially for push applications, not suitable for pull.

TL3 Direct Cut Ordering Key

TL3

Version: 20170613-J

Voltage	5 = 24V DC, thermal protector		
Load and Speed	See page 82		
Stroke (mm)	100-1200		
Restracted Lengh (mm)	See page 88		
Cable Exit See page 90	B = Top side- for TH; Bottom side- for TP C = Bottom side - Y cable, for TH + TP D = Top side - for the 2nd column; bottom side - for TH & TP; direct cut operation with 2 columns E = Top side - for the 2nd column & TH; bottom side - for TP; direct cut operation with 2 columns		
Special Functions for Spindle Sub-Assembly	0 = Without (Standard)		
Functions for Limit Switches See page 89	1 = Two switches at full retracted/extended positions to cut current		
IP Rating	1 = Without	2 = IPX4	3 = IPX6
Output Signals	0 = Without		
Connector See page 91	C = Direct cut, water proof, anti-pull		
Cable Length (mm)	B = Cable exit #B, L2=L3=100 C = Cable exit #C, L1=L2=L3=100 D = Cable exit #D, L2=L3=L4=100 E = Cable exit #E, L2=L3=L4=100		

NOTE

1 TL3 is designed especially for push applications, not suitable for pull.

TL3

Ordering Key Appendix

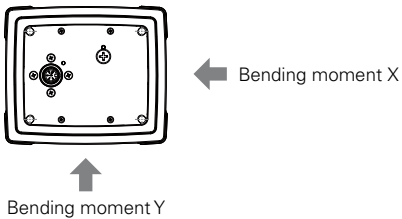
Retracted Length (mm)

1. Minimum retracted length needs to $\geq A+B+C$

A. Retracted Length (mm)	Load (N)			
	1000	2000	4000	
	Stroke/ 2+150 or Stroke/ 2+220*			
B. Cable Exit	Code	Type		
		Top end socket	Side cable	Direct Cut
	1	-	-	-
	2,3	-	+20	-
	B,D,E	-	-	+40
	C	-	-	+20
C. Output Signal	Code	Cable exit (with POT)		
		Top end socket	Side cable	
		1	2	3
	C	+40	+20	+40

*Different retracted length is relative to the following diagram-Dynamic bending moment (Nm)- X direction.

Dynamic bending moment (Nm)- X direction	Stroke (mm)	Retracted Length (mm)	
		S/2+150	S/2+220
	100-300	700	1000
	301-500	500	800
	501-700	300	500
	701-1200	200	200









NOTE

- 1 Bending moment Y direction= $X \cdot 0.8$
- 2 Static bending moment= dynamic*2

Functions for Limit Switches

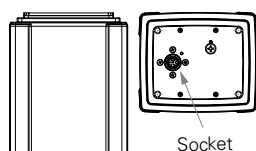
Wire Definitions

		CODE	
	Pin	1	3
 Green	1	Extend (VDC+)	Extend (VDC+)
 Red	2	N/A	Common
 White	3	N/A	Upper limit switch
 Black	4	N/A	N/A
 Yellow	5	Retract (VDC+)	Retract (VDC+)
 Blue	6	N/A	Lower limit switch

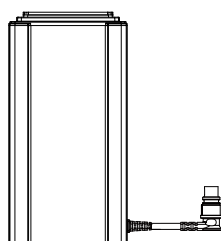
NOTE

¹ See ordering key - functions for limit switches.

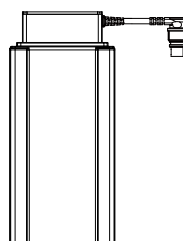
Cable Exit



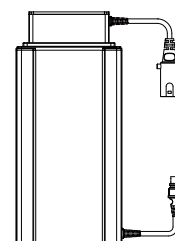
1 = Top end socket



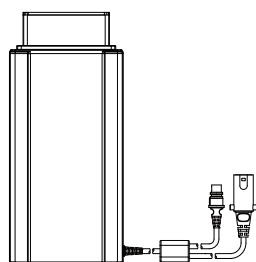
2 = Bottom side cable



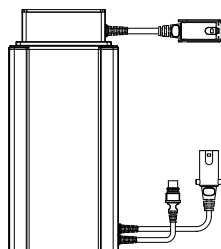
3 = Top side cable



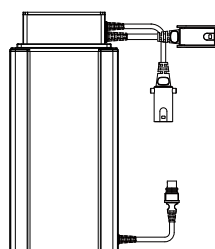
B = Top side- for TH; Bottom side- for TP



C = Bottom side- Y cable, for TH + TP

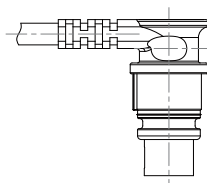


D = Top side- for the 2nd column; Bottom side- for TH & TP

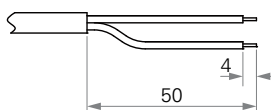


E = Top side- for the 2nd column & TH; Bottom side- for TP

Connector



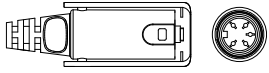
1 = DIN 6P, 90° plug



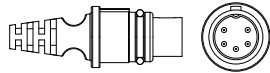
2 = Tinned leads



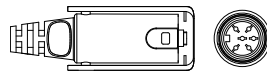
F = DIN 6P, 180° plug



C = Directcut, water proof,
anti-pull.
For TH: long DIN 5P
(Pin array 240°),180° socket
(with anti-pull clip)



C = Directcut, water proof,
anti-pull.
For TP: long DIN 5P
(Pin array 240°),180° plug
(with O-ring)



C = Directcut, water proof,
anti-pull.
For Column 2: long DIN 6P
(Pin array 240°),180° socket
(with anti-pull clip)



TiMOTION's TL18 series electric lifting columns are designed for industrial applications like electric height adjustable workstations and screen or lifting tables. The TL18 is features an extruded aluminum rectangular appearance. Our high capacity, yet economical, TL18 provides stable vertical lifting. This streamlines the engineering design process and replaces the older style, unsafe lifting mechanisms which have many moving stages and pinch points.

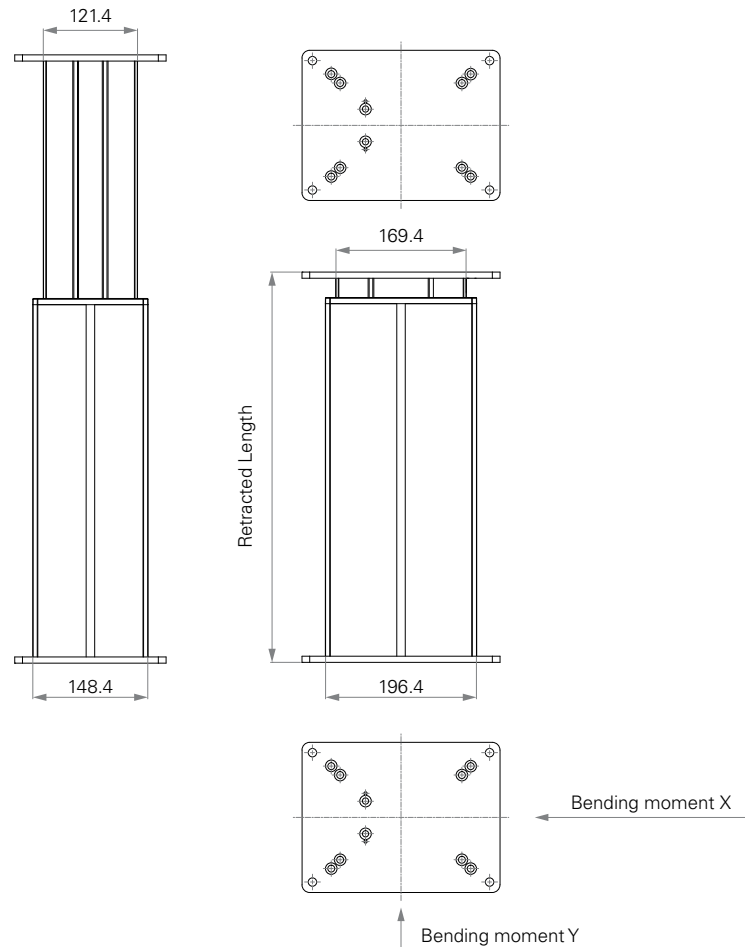
Load and Speed

	CODE	Load (N)	Bending Moment-X Direction (Nm)		Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)	
			Dynamic	Static		No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (3800RPM)	U	4500	250	500	4500	2.5	4.9	11.4	6.6
	Z	3000	250	500	3000	2.5	5.5	17.1	9.5
	W	2000	250	500	2000	2.5	4.8	22.9	13.1
	S	1500	250	500	1500	2.5	4.7	30.0	18.9
	V	500	250	500	500	2.5	4.0	45.0	28.0

NOTE

- 1 With a 12V motor, the current is approximately twice the current measured in 24V; speed will be similar for both voltages.
- 2 Self locking force: Tested average value when working with TiMOTION control system.
- 3 Y direction= $X \times 0.8$

Standard Dimension (mm)



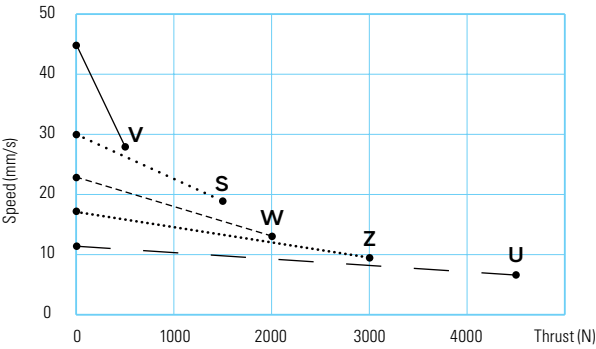
General Features

Maximum load	4,500N in push
Maximum dynamic bending moment	250Nm
Maximum static bending moment	500Nm
Maximum speed at full load	28mm/s (with 500N in a push condition)
Minimum installation dimension	Stroke+147mm
Stroke	100~700mm
Operational temperature range	+5°C~+45°C
Options	Hall sensor(s), cable exit from top or bottom side

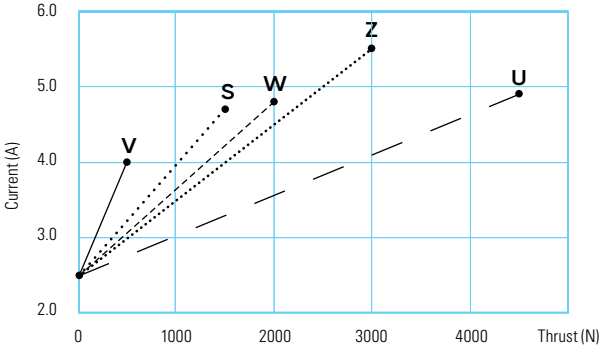
Performance Data

Motor Speed 24V 3800RPM

Speed vs. Thrust



Current vs. Thrust



NOTE

1 The performance data in the curve charts shows theoretical value.

TL18 Ordering Key

TL18

Version: 20170711-E

Voltage	1 = 12V DC	2 = 24V DC	
Load and Speed	See page 92		
Stroke (mm)	100~700		
Restracted Lenght (mm)	See page 96		
Cable Exit See page 98	2 = Bottom side cable	3 = Top side cable	
Special Functions for Spindle Sub-Assembly	0 = Without (standard)	1 = Safty nut	
Functions for Limit Switches	1 = Two switches at full retracted / extended positions to cut current	3 = Two switches at full retracted / extended positions to send signal	
Color	1 = Body - white (anodized) ; top / bottom plates - black (electrodeposition) 2 = Body - black (anodized) ; top / bottom plates - black (electrodeposition)		
IP Rating	1 = Without		
Output Signals	0 = Without	2 = Two Hall Sensors	
Top Plate	1 = Small	2 = Big	
Bottom Plate	1 = Small	2 = Big	
Connector See page 98	1 = DIN 6P, 90° plug	C = Y cable, for direct cut system	E = MOLEX 8P, plug
Cable Length (mm) See page 98	1 = Straight, 500 2 = Straight, 750 3 = Straight, 1000	4 = Straight, 1250 5 = Straight, 1500 6 = Straight, 1750	A = For direct cut system, please See page 98

TL18

Ordering Key Appendix







Retracted Length (mm)

1. Retracted length needs to \geq Stroke+A

A. Plate	Top Plate	Bottom Plate	
		1	2
	1	+147	+151
	2	+151	+155

Functions for Limit Switches

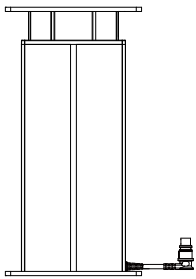
Wire Definitions

Wire Definitions			CODE	
		Pin	1	3
	Green	1	Extend (VDC+)	Extend (VDC+)
	Red	2	N/A	Common
	White	3	N/A	Upper limit switch
	Black	4	N/A	N/A
	Yellow	5	Retract (VDC+)	Retract (VDC+)
	Blue	6	N/A	Lower limit switch

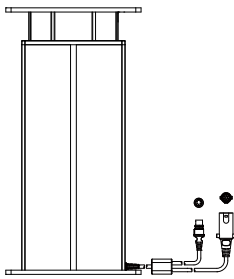
NOTE

² See ordering key - functions for limit switches.

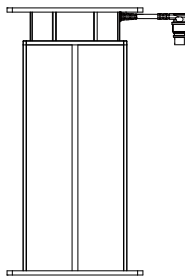
Cable Exit



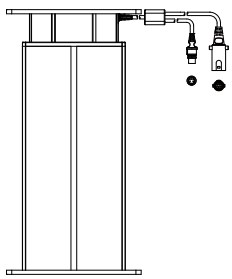
2 =Bottom side cable



2 = Bottom side - Y cable for TH + TP (directcut system)

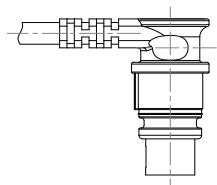


3 = Top side cable

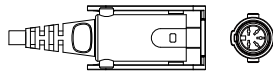


3 =Top side - Y cable for TH + TP (directcut system)

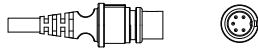
Connector



1 = DIN 6P, 90° plug

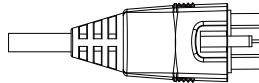


For TH: Long DIN 5P, 180° socket (with anti pull clip)



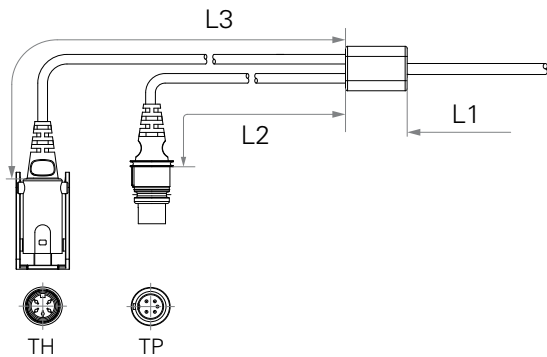
For TP: Long DIN 5P, 180° plug (with O ring)

C = Y cable, for direct cut system



E = MOLEX 8P, plug

Cable Length



A = For direct cut system

Cable Length for Direct Cut System	For Length	TL	TP	TH
		L1:100	L2:100	L3:100

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as well as the people and wildlife
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